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Applied Soft Computing

journal homepage: www.elsevier.com/locate/asoc

Hybrid particle swarm optimization algorithm for solving the clustered vehicle routing problem

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a r t i c l e i n f o

Article history: Received 18 September 2019 Received in revised form 21 June 2021 Accepted 23 June 2021 Available online 30 June 2021

Keywords: Clustered vehicle routing problem (CluVRP) Particle swarm optimization (PSO) VNS Hybrid metaheuristic

a b s t r a c t

This paper considers a variant of the classical capacitated vehicle routing problem called clustered vehicle routing problem (CluVRP). In CluVRP, customers are grouped into different clusters. A vehicle visiting a cluster cannot leave the cluster until all customers in the same cluster have been served. Each cluster and customer have to be served only once. A new hybrid metaheuristic, combining the particle swarm optimization (PSO) and variable neighborhood search (VNS) for the specific problem, is proposed to solve the CluVRP. In the hybrid PSO, the basic PSO principle ensures the solution diversity and VNS ensures solution intensity to bring the solution to the local optima. Extensive computational experiments have been performed on numerous benchmark instances with various sizes obtained from the CluVRP literature to evaluate the performance of the proposed hybrid PSO. The obtained results of the proposed algorithm are compared with the results found in the literature to validate the effectiveness of the proposed hybrid PSO. The proposed algorithm is proven to be superior to the state-of-the-art algorithms on the CluVRP. The proposed algorithm obtains 138 new best-known solutions among the 293 benchmark instances.

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1. Introduction

The typical vehicle routing problem (VRP) is a logistic distribution problem. The VRP aims to obtain a list of least-cost vehicle routes serving many geographically scattered customers under various supply and demand constraints. It is a combinatorial optimization problem that requires exponential computational time to be optimized. This study presents a variant of the capacitated vehicle routing problem (CVRP) called the Clustered VRP (CluVRP). In CluVRP, customers are partitioned into predefined groups called clusters. The customers corresponding to a single cluster must all be visited by the same vehicle before it leaves the cluster. The notion of clustering in VRP has been well known due to its economic implications and its reduced complexity in modeling and solving a great range of real-world applications [[1\]](#page-11-0). The CluVRP is a generalized form of the CVRP. As the CVRP is proven to be an NP-hard problem, the CluVRP is also NP-hard [[2\]](#page-11-1).

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There are two variants of CluVRP such as CluVRP with strong cluster constraints (CluVRP) and CluVRP with weak cluster constraints (SoftCluVRP). In the CluVRP, all customers belong to the same cluster must be visited uninterruptedly by the same vehicle. Vehicles are not permitted to enter and leave clusters several times while serving the customers. In the SoftCluVRP, though customers belong to a specific cluster are visited by the same vehicle, but vehicles are allowed to leave and enter clusters many times during their trip in the route. This paper studies a CluVRP with strong cluster constraints referred as CluVRP. The CluVRPs are explored in many studies such as [\[1](#page-11-0)[,3–](#page-11-2)[10](#page-11-3)] and SoftCluVRPs are studied in the works of $[8,10,11]$ $[8,10,11]$ $[8,10,11]$ $[8,10,11]$. Most of the studies in the literature proposed metaheuristics based solution approaches.

The comprehensive CluVRP introduced by Sevaux and Sörensen [[12\]](#page-11-6) focused on a real-world parcel delivery problem in courier companies. The consignment parcels were arranged into bins corresponding to the specific delivery zones. The consignees belonged to the same zone designated as a cluster. The CluVRP can also arise in many scenarios such as transporting elderly people when the customers prefer to move with friends or neighbors, providing service to gated communities, collecting urban solid waste, providing the services of common repairmen, delivering

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healthcare providing service in both precedence ordered multitude of emergency environments and in logistics operations in an order-picking [[1](#page-11-0)[,13](#page-11-7)].

The key contribution of this paper is to design a hybrid metaheuristic for solving a CluVRP. The proposed metaheuristic algorithm is based on the combination of particle swarm optimization (PSO) and the CluVRP specific variable neighborhood search (VNS). The VNS helps to discover the local optimal solution of the search region. In the literature, VNS has been implemented mostly to improve particle solutions. But, this paper uses VNS to improve personal best solutions along with the global best solution by using improvement scheme. The contribution also includes the use of new features in the PSO algorithm such as the use of two types of particles. This hybrid PSO is targeted to achieve a better quality solution for the CluVRP problem.

The rest of the paper is structured as herein described. The literature of CluVRP is reviewed in Section [2.](#page-1-0) In Section [3,](#page-2-0) the CluVRP is defined, and its mathematical formulation is presented. The proposed hybrid PSO is discussed in detail in Section [4.](#page-2-1) The computational results are reported in Section [5.](#page-5-0) Finally, the conclusion is stated in Section [6](#page-9-0).

2. Literature review

Sevaux and Sörensen [[12](#page-11-6)] proposed a mixed integer linear programming formulation of a CluVRP for a distribution operation in a famous courier services company. Barthélemy et al. [[3\]](#page-11-2) designed a heuristic for a CluVRP, where a big value was added to all inter-cluster edges to convert the CluVRP into a CVRP and solve it by simulated annealing method. Pop et al. [[4\]](#page-11-8) presented two integer programming based exact solution approaches for a CluVRP. In another study, based on the integer programming formulation, two exact solution approaches such as branch-andcut and branch-and-cut-and-price were presented by Battarra et al. [[5\]](#page-11-9). A new hybrid algorithm based on the genetic algorithm combined with simulated annealing was developed to solve a CluVRP by Marc et al. [\[6](#page-11-10)]. Vidal et al. [\[7](#page-11-11)] proposed two hybrid metaheuristics for solving a CluVRP. The first one was based on the iterated local search (ILS) algorithm designed by Subramanian [\[14\]](#page-11-12). The second one was based on the unified hybrid genetic search (UHGS). An approximate two-level optimization technique was suggested to solve a CluVRP in Expósito-Izquierdo et al. [[1](#page-11-0)]. Defryn and Sörensen [\[8](#page-11-4)] developed an efficient two-level variable neighborhood search (VNS) heuristic to solve a CluVRP. A study by Pop et al. [[9\]](#page-11-13) addressed a unique two-level optimization approach to solve a CluVRP. The problem was divided into two sub-problems: the upper-level (cluster) sub-problem and the lower-level (customer) sub-problem. In the approach, the route visiting the clusters was obtained by a genetic algorithm, then, the customers' visiting order within the clusters was determined by the Concorde TSP solver. The recent trend of metaheuristics shows its hybridization for performance improvement. Recently, Hintsch and Irnich [[10\]](#page-11-3) presented a large multiple neighborhood search (LMNS) based metaheuristic algorithm for the CluVRP. The problem was broken down into three sub-problems: assigning clusters to the routes, intra-cluster routing, and routing the clusters. In the LMNS approach, multiple destroy and repair moves for clusters were used first, then a VND-based local search improvement scheme was employed for further optimization. Most of the hybridization is done through the use of local search schemes. This observation motivated us to hybridize the PSO to improve its performance in this study.

Our current paper proposes a solution approach based on classical particle swarm optimization (PSO) combined with a variable neighborhood search (VNS) for solving a CluVRP. The PSO is a population-based combinatorial optimization technique originally familiarized in Eberhart and Kennedy [[15](#page-11-14)]. The technique has been inspired by social collective behaviors seen in many natural swarms such as bird flocking, fish schooling, and human beings. The hybridized PSO approaches were used in many variants of VRPs such as hybridized with local searches in Ai and Kachitvichyanukul [[16](#page-11-15)]; with local searches and path relinking strategy in Marinakis et al. [\[17\]](#page-11-16) and with modified local search in Norouzi et al. [[18](#page-11-17)]. Additionally, an adaptive PSO algorithm was built to solve an integrated quay crane and yard truck scheduling problem successfully [\[19](#page-12-3)]. Dridi et al. [\[20\]](#page-12-4) developed a new PSO based solution approach for an optimization problem of multidepots pick-up and delivery problems with time windows and multi-vehicles. It is clear from the literature that the efficiency of PSO can be improved by its hybridizing.

PSO algorithm has many advantages such as few parameters to tune, easy to implement, and requires less server memory compared to other metaheuristics. PSO algorithm is successfully utilized and found as a validated solution method for many combinatorial optimization problems in the areas of transport, manufacturing, and scheduling problems [\[21](#page-12-5)–[23](#page-12-6)]. The VNS uses multiple local search methods to obtain the local optimum. The PSO has the ability to diversify the solution while VNS has the ability to intensify the solutions. These strengths are combined in our proposed metaheuristic algorithm.

The variable neighborhood search (VNS) was first introduced by Mladenovic and Hansen [[24](#page-12-7)] to solve a traveling salesman problem in 1997. Usually, a VNS is used as a local search algorithm to obtain the local best solution $[25]$. The VNS is also a widely used heuristic search method in VRPs [\[26](#page-12-9)]. Many studies found using the VNS with the PSO for solving several optimization problems, where PSO solution used as a global search algorithm. Marinakis et al. [\[27\]](#page-12-10) generated a hybrid PSO metaheuristic to solve a CVRP, by producing an initial solution from a greedy randomized adaptive search procedure and by improving the solution further by a VNS algorithm. Goksal et al. [[28](#page-12-11)] introduced a hybrid metaheuristic based on PSO and variable neighborhood descent (VND), a lower-level VNS, to solve a vehicle routing problem with simultaneous pickup and delivery. Besides, Marinakis et al. [\[29\]](#page-12-12) proposed a multi-adaptive PSO solution approach for a vehicle routing problem with time windows, where the PSO solutions were improved by applying VNS for each particle in the swarm. Zou et al. [\[30\]](#page-12-13) presented a novel PSO algorithm hybridized with VNS to solve a multi-objective VRP with pickup and delivery problems with time windows. Zhang et al. [\[31\]](#page-12-14) designed a hybrid solution based on VNS integrated with binary PSO to solve a location-routing problem (LRP). Marinakis [[32\]](#page-12-15) hybridized a PSO combined with a VNS for solving a capacitated LRP. In another study, Moghaddam et al. [\[33](#page-12-16)] used VNS in an advanced PSO based solution approach to solve a vehicle routing problem with uncertain demands. A novel decoding algorithm was used to increase the efficiency of the solution approach. The decoding was designed for generating vehicle routes and updating particle values. Moreover, due to the dominant behavior of PSO in producing a strong global solution and VNS having the advantages of generating the best local solution, PSO and VNS have also been used widely in job scheduling problems [[34](#page-12-17)]. Liu et al. [\[35\]](#page-12-18) used a hybrid metaheuristic based on PSO combined with VNS to solve a multi-objective flexible job-shop scheduling problem. In additional work [\[36\]](#page-12-19), it was shown that a simpler VNS algorithm without hybridization with PSO produces a better quality solution with shorter CPU time than a hybrid PSO with a VNS algorithm for the job-shop scheduling problems. Furthermore, a hybrid metaheuristic combining a PSO and VNS algorithm was proposed for solving an unconstrained global optimization problem in Ali et al. [\[37\]](#page-12-20). In the study, the PSO was used to perform a wider diversification and deep intensification in the solution space, and VNS was used as a local search algorithm. Furthermore, a PSObased hybrid metaheuristic was designed for permutation flow

shop scheduling problems [[38](#page-12-21)]. In the work, a PSO algorithm was incorporated with a stochastic VNS, a variant of VNS proposed in [[32](#page-12-15)], hybridized with simulation annealing to enhance the exploration ability of PSO in the solution approach. Gumaida and Luo [[39](#page-12-22)] developed a new hybrid optimization technique based on PSO combined with a VNS to enhance the localization process in wireless sensor networks. Marinakis et al. [\[40](#page-12-23)] designed a hybrid PSO incorporated with VNS to solve a constrained shortest path problem. Cai et al. [\[41](#page-12-24)] proposed a hybrid PSO based solution approach where the PSO was hybridized by VNS to solve a VRP with speed variables through reduced carbon emissions in the routes. A railway cargo transportation problem was studied by proposing a solution method based on PSO with VNS in Nie et al. [[21\]](#page-12-5). Ranjbar and Saber [[42](#page-12-25)] designed a VNS and modified PSO based solution approaches for a transshipment scheduling problem of multi-products at a single station. Islam et al. [\[43\]](#page-12-26) presented a PSO and VNS based solution approach for solving a mixed fleet green logistics problem under carbon emission cap. Motivated by this observation, this paper embeds the VNS with the PSO to obtain a good quality solution of the CluVRP.

3. Problem definition of CluVRP

The CluVRP can be defined on an undirected graph $G = (V, E)$, where $V = \{0, 1, 2, \ldots, n\}$, a set of nodes (vertices) including the customers $\{1, 2, \ldots, n\}$, *E* is the set of arcs linking each pair of nodes (*i*, *j*) in *V*, and a depot 0. A homogeneous fleet of vehicles is situated at the depot, where the vehicles start and end their trip while serving the customers.

Parameters

The binary decision variables are:

 $x_{ijm} = \begin{cases} 1 & \text{ vehicle } m \text{ travels from customer } i \text{ to } j \end{cases}$ 0 otherwise $y_{im} = \begin{cases} 1 & \text{customer } i \text{ is served by vehicle } m \\ 0 & \text{otherwise.} \end{cases}$ 0 otherwise

The CluVRP can be formulated as follows:

Minimize
$$
\sum_{(i,j)\in E} \sum_{m=1}^{M} t c_{ij} x_{ijm}
$$
 (1)

s.t.,
\n
$$
\sum_{mn}^{M} y_{im} = 1 \qquad \forall i \in \{1, 2,
$$

$$
\sum_{m=1}^{M} y_{0m} \leq M \tag{3}
$$

$$
y_{0m} \ge y_{im} \qquad \forall m \in \{1, 2, ..., M\}, \forall i \in \{1, 2, ..., n\}
$$
 (4)

$$
\sum_{j=1}^{n} x_{ijm} = \sum_{j=1}^{n} x_{jim} = y_{im}
$$
\n
$$
\forall m \in \{1, 2, ..., M\}, \forall i \in \{0, 1, 2, ..., n\}
$$
\n(5)

$$
\sum_{i=0}^{n} d_i y_{im} \le Q \qquad \forall m \in \{1, 2, ..., M\}
$$
 (6)

∑ *i*∈*S* ∑ *j*∈*V**S* $x_{ijm} \geq y_{hm}$

$$
\forall S \subseteq \{1, 2, ..., n\}, h \in S, m \in \{0, 1, 2, ..., M\}
$$
\n(7)

$$
\sum_{(i,j)\in\delta^{+}(C_{r})}\sum_{m=1}^{M}x_{ijm}=\sum_{(i,j)\in\delta^{-}(C_{r})}\sum_{m=1}^{M}x_{ijm}=1 \qquad \forall r\in R
$$
 (8)

$$
\sum_{i=1}^{n} d_i y_{im} \ge \sum_{i=1}^{n} d_i y_{im+1} \qquad \forall m \in \{1, 2, ..., M-1\}
$$
 (9)

$$
x_{ijm} \in \{0, 1\} \qquad \forall (i, j) \in E, \forall m \in \{1, 2, ..., M\}
$$
 (10)

$$
y_{im} \in \{0, 1\} \qquad \forall i \in \{0, 1, 2, \dots, n\}, \forall m \in \{1, 2, \dots, M\} \tag{11}
$$

The objective of minimizing the total travel cost is determined by Eq. [\(1](#page-2-2)). Constraint ([2\)](#page-2-3) guarantees that each customer is visited exactly once. Constraint [\(3](#page-2-4)) assures that the number of vehicles used does not exceed the number of available vehicles. Constraint ([4](#page-2-5)) enforces the rule that each vehicle in the route should visit the depot. If a vehicle *m* does not visit the depot then it should not visit any customer. Constraint [\(5\)](#page-2-6) ensures that the arriving and the departing vehicle is the same for a given customer. Constraint [\(6\)](#page-2-7) states the maximum loading capacity of the vehicles is satisfied. Constraint [\(7](#page-2-8)) represents the sub-tour elimination constraint. Constraint [\(8](#page-2-9)) ensures that each cluster can be visited exactly once by a unique vehicle. Constraint (9) is the inequality ensuring partial symmetry.

4. Proposed hybrid PSO for the CluVRP

The proposed approach is a hybrid PSO algorithm that combines the standard PSO and the VNS. The structure of VNS in the proposed approach is inspired by a study by Vidal et al. [[7\]](#page-11-11). Generally, the performance of the PSO is largely affected by the accuracy of the problem mapping. Thus, the PSO is modified in accordance with problem specifications in this study. The main features of the proposed hybrid PSO are the use of two types of particles representing clusters and customers, and the use of an improvement scheme for the personal best solutions. The pseudo code of the proposed hybrid PSO is shown in Algorithm 1.

The proposed hybrid PSO uses the following definition:

- α*il* Current cluster position value of *i*th particle in *l*th dimension
- γ*ij* Current customer position value of *i*th particle in *j*th dimension
- β*il* Current cluster velocity value of *i*th particle in *l*th dimension
- δ*ij* Current customer velocity value of *i*th particle in *j*th dimension
- *fⁱ* Fitness function of particle, *i*

Algorithm 1: Pseudo code of the proposed algorithm

 $14:$ End Do

4.1. Initialization phase

The position and velocity vectors are initialized as follows:

$$
\alpha_{il} = \alpha_{min} + (\alpha_{max} - \alpha_{min}) * U(0, 1)
$$

\n
$$
\forall i \in \{1, 2, \dots K\}, \forall l \in \{1, 2, \dots c\}
$$

\n
$$
\gamma_{il} = \gamma_{min} + (\gamma_{max} - \gamma_{min}) * U(0, 1)
$$
\n(12)

$$
\forall i \in \{1, 2, ..., K\}, \forall j \in \{1, 2, ..., n\} \n\delta_{il} = \delta_{min} + (\delta_{max} - \delta_{min}) * U(0, 1)
$$
\n(13)

$$
\forall i \in \{1, 2, ..., K\}, \forall l \in \{1, 2, ..., c\}
$$
 (14)

$$
\beta_{il} = \beta_{min} + (\beta_{max} - \beta_{min}) * U(0, 1)
$$

\n
$$
\forall i \in \{1, 2, ..., K\}, \forall j \in \{1, 2, ..., n\}
$$
 (15)

Where $\alpha_{max} = \gamma_{max} = \delta_{max} = \beta_{max} = 4$; $\alpha_{min} = \gamma_{min} = \delta_{min} =$ $\beta_{min} = -4.$

Here, *U*(0, 1) represents a uniform random number generated between 0 and 1. The personal best fitness vector for the particle, *i* and fitness vector of a global particle are initialized as infinity.

$$
f_i^b = \infty \quad \forall i \in \{1, 2, ..., K\}
$$

$$
f^g = \infty
$$

Table 1

An instance with 6 clusters with their position values and demands in any iteration, *t*.

Clusters					
Position values, α_{il} Cluster demand, d_r	1.99 45	3.67	-2.25	-0.09	l.O8

4.2. Mapping position vectors to generate CluVRP solution

The PSO usually maps the position values of the particles to generate the solution for a given problem. The position values are used to generate the CluVRP solution (*S*← GenerateCluVRP-Solution (*X*, *Y*, *U*, *V*)) as stated in line 8 in algorithm 1. The two-phase approach is used in many studies to generate CluVRP solutions [\[8](#page-11-4)[,9\]](#page-11-13). In the proposed PSO, the solution is generated in two phases. In the first phase, the cluster route for the vehicles is generated from the position values of clusters α_{il} , while the customer route for each cluster is generated in the second phase from the position values of customers γ*ij*.

4.2.1. Generating cluster route

The generation of the cluster route starts with the empty trip for each vehicle, where the vehicles start and finish their trip at the depot. The clusters are iteratively added to the vehicle routes to find the complete solution. Firstly, the clusters with the highest position values are chosen for inclusion in the vehicle route, then the chosen cluster is inserted into the vehicle routes by using the cheapest insertion method. However, cluster insertion might face a situation where no vehicle has enough capacity for inserting a chosen cluster. In this situation, a tabu search based searching method is used to insert the chosen cluster. This method tries to maximize the available vehicle capacity using swap (1,1) and shift (1,0) neighborhood move. The selected swap move between clusters *i* and *j* is forbidden for next $U\left(\frac{c^2}{8}\right)$ $\frac{c^2}{8}, \frac{c^2}{4}$ $\frac{c^2}{4}\Big)$ iterations. Similarly in shift (1,0) move, insertion of cluster *i* is forbidden in cluster *j* for next $U\left(\frac{c*v}{8}, \frac{c*v}{4}\right)$ iterations.

To understand the mapping procedure for cluster routes, consider an instance with 6 clusters and 2 vehicles with a vehicle capacity of 80. In any iteration *t*, consider the following cluster position values for *i*th particle in *l*th dimension as shown in [Ta](#page-3-0)[ble](#page-3-0) [1.](#page-3-0) In this example, 6 different dimensions represent 6 different clusters. Since different dimensions are associated with different clusters, we refer the cluster position value of *l*th dimension as a position value of *l*th cluster.

In the mapping, clusters are arranged in non-increasing order of their position values. The resultant order is $\pi = 2-4-1-6-5-3$. The two vehicles routes initially start with the first two clusters from π . The initial route is {0-2-0; 0-4-0} and the remaining vehicle capacity for each vehicle is updated accordingly. Then, cluster 1 is chosen for insertion on vehicle routes. The insertion cost (i.e., increase in total route length) of cluster 1 is evaluated on every position of two routes {0-2-0; 0-4-0}. Suppose the cheapest insertion of cluster 1 is obtained by inserting at position 3 of vehicle 2. Then the new route is {0-2-0; 0-4-1-0}. In the next iteration, cluster 6 is chosen for insertion. Suppose the cheapest insertion of cluster 6 is obtained by inserting at position 3 of vehicle 1. Then the new route is {0-2-6-0; 0-4-1-0}. In the next iteration, cluster 5 is chosen for insertion. Suppose the cheapest insertion of cluster 5 is obtained by inserting at position 2 of vehicle 1. Then the new route is {0-5-2-6-0; 0-4-1-0}. At this point, the remaining capacities for the two vehicles are 15 and 20. But the demand for unassigned cluster 3 is 25 and no vehicle has the required capacity to accommodate cluster 3. In this situation, we use the tabu search with swap $(1, 1)$ and shift $(1, 0)$ with the objective function of maximizing the remaining vehicle

A vehicle route of 2 clusters with their customers and position values in any iteration, *t*.

Cluster 1	Customers Position values, y_{ii}	10 2.74	3.44	-1.81	
Cluster 3	Customers Position values, y_{ii}	2.03	-0.96	1.60	1.87

capacity. The tabu search is stopped when the objective function (i.e., remaining vehicle capacity) becomes at least 25. Let assume the tabu search finds the new routes as {0-4-5-2-6-0; 0-1-0}. The remaining capacities are 0 and 35 for vehicle 1 and vehicle 2 respectively. Finally, cluster 3 is chosen for insertion. Suppose the cheapest insertion of cluster 3 is obtained by inserting at position 3 on vehicle 2. Consequently, the final routes is {0-4-5-2-6-0; 0-1-3-0}.

4.2.2. Generating customer route

Once the cluster routes are constructed, a sequence of the customers for each cluster is generated to find the complete solution of the CluVRP. The sequence of the customers is generated by selecting customers similar to the clusters routes generation method described in Section [4.2.1](#page-3-1).

To understand the generation of customer routes, consider a cluster route in a vehicle is {0-1-3-0}. Suppose there are 3 customers and 4 customers in cluster 1 and cluster 3 respectively as shown in [Table](#page-4-0) [2](#page-4-0). In any iteration *t*, consider the following customer position values for *i*th particle in *j*th dimension as stated in [Table](#page-4-0) [2.](#page-4-0) Since different dimensions are associated with different customers, we refer the position value of *j*th dimension as a position value of *j*th customer.

In the customer routes generation, customers are arranged in non-increasing order of their position values. The resultant customer order for cluster 1 is $\tau = 4 - 10 - 7$ and cluster 3 is $\tau = 2-5-9-17$. The complete customer route of the vehicle is {0-4-10-7-2-5-9-17-0}. The travel cost (i.e., objective function value) of the route is the sum of the travel costs of all customers in the route.

4.3. Variable neighborhood search (VNS) for CluVRP

The proposed PSO considers the position vector as a region instead of a particular point. The solution generated in the mapping phase represents one solution in the region, which might not be the best solution of the region. Therefore, the VNS is employed to achieve the local optima. The VNS procedure consists of three local search moves, which are inter-route search, intra-route search, and intra-cluster search. Both the inter-route search and intra-route search focus on the cluster level; whereas, the intracluster search focuses on the customer level. The neighborhood operators which are used at cluster level: shift, shift2, swap, swap (2,1), swap (2,2), and 2-opt in the inter-route search; and shift, or-opt2, or-opt3, 2-opt, and swap in the intra-route search. The *NL^c* is the list of all inter-route neighborhood searches. The neighborhood operators that are adopted for intra-cluster search (customer level) are shift, 2-opt, and swap; these explore all moves within each cluster. The detail of the operators can be found in the literature [\[7](#page-11-11),[14,](#page-11-12)[44](#page-12-27)]. The structure of each operator is shown in [Figs.](#page-4-1) [1](#page-4-1) and [2](#page-5-1). The first move adoption strategy is adopted for all local search moves. In this strategy, the solution is updated whenever an improved solution is found. In all local searches, each neighborhood move is selected only once for possible improvement instead of iterative strategy. The overall structure of the VNS is shown in Algorithm 2.

Fig. 1. Inter-route neighborhood search operators.

Algorithm 2: Variable neighborhood search (VNS)

dia na matatagpia

Fig. 2. Intra-route and inter-cluster neighborhood search operators.

4.4. Updating position and velocity vectors

The personal best position value for each particle is updated if the current solution obtained is better than the current personal best solution. Similarly, the global best value is updated if the new best solution is found better than the current global best value.

The velocity and position vectors are updated as follows:

$$
\delta_{il} = w \delta_{il} + c_1 r_1 \left(\alpha_l^p - \alpha_{il} \right) + c_2 r_2 \left(\alpha_l^* - \alpha_{il} \right)
$$

\n
$$
\forall i \in \{1, 2, \dots, K\}, \forall l \{1, 2, \dots, c\}
$$
 (16)

$$
\beta_{il} = w\beta_{il} + c_1r_1\left(\gamma_j^p - \gamma_{il}\right) + c_2r_2\left(\gamma_j^* - \gamma_{il}\right)
$$

$$
\forall i \in \{1, 2, \dots, K\}, \forall j \{1, 2, \dots, n\}
$$
\n(17)

$$
\alpha_{il} = \alpha_{il} + \delta_{il} \qquad \forall i \in \{1, 2, \ldots, K\}, \forall l \{1, 2, \ldots, c\}
$$
 (18)

$$
\gamma_{il} = \gamma_{il} + \beta_{il} \qquad \forall i \in \{1, 2, ..., K\}, \forall j \{1, 2, ..., n\}
$$
 (19)

4.5. Improvement scheme

The improvement scheme is used to improve the personal best solution. This is one of the new features of PSO used in this study. To our knowledge, this feature is not used in the existing literature of PSO. In the improvement scheme, at first, the solution is perturbed to generate a new solution. The perturbed solution is then optimized using the VNS scheme. A perturbation technique is implemented in both cluster and customer levels. In the perturbation scheme, firstly the Δ_1/Δ_2 number of clusters/customers are removed and then reinserting again using the

cheapest insertion method. The structure of the improvement scheme is shown in Algorithm 3. The parameters $\overline{\Delta}_1$ and $\overline{\Delta}_2$ are randomly generated between [0.5c, 0.75c] and [0.5*nl*, 0.75*nl*] respectively.

Algorithm 3: Improvement scheme

4.6. Computational complexity of hybrid PSO

There are four main steps in the hybrid PSO algorithm- (1) sequence generation, (2) VNS method, (3) parameter update and (4) improvement scheme. The sequence generation step first creates route for clusters. The cluster route generation performs two sequential operations- (a) arranging clusters according to the position values, and (b) inserting clusters in partially generated routes. Both operations can be performed in $O(c^2)$ time, the complexity of the cluster route generation step remains $O(c^2)$. After generating cluster routes, the sequence generation step creates routes of the customer, which can be performed in $O(n^2)$ time. Since the cluster route generation and the customer route generation are performed sequentially, the complexity of sequence generation step becomes $O(c^2 + n^2)$. Similarly, VNS method, parameter updating, and improvement scheme can be performed in $O(c^2 + n^2)$ time. The four steps of the PSO are performed sequentially, therefore the complexity of one iteration of hybrid PSO remains $O(c^2 + n^2)$.

5. Computational experiments

The proposed hybrid PSO algorithm is implemented using the C++ programming language to solve several benchmark datasets from the literature of CluVRP. The experiments are run on a Linux server with four 2.1 GHz processors with 16-core each and a total of 256 GB of RAM.

5.1. The benchmark CluVRP instances

The performance of the hybrid-PSO is tested on the CluVRP benchmark instances composed of 20 major customer groups named as, A, B, P, M, and Golden instances (Golden 1 to Golden 20) with a total of 298 individual instances. These CluVRP instances are originally adopted from the GVRP instances by Bektas et al. [[45](#page-12-28)]. The characteristics of the benchmark dataset are summarized in [Table](#page-6-0) [3](#page-6-0). The algorithms and their notations used in this study for the results reporting purpose are shown in [Table](#page-6-1) [4.](#page-6-1)

The PSO parameters are set by performing sensitivity analysis using the problem instances of sets A, B, M, and P. We use PSO solution without VNS and without improvement scheme for 100 iterations to set the parameters. We start the sensitivity analysis with the parameter values found in the literature [\[16,](#page-11-15)[17,](#page-11-16)[27](#page-12-10)]. The parameter values are set one by one in the order of w , c_1 , c_2 , r_1 , r_2 , and *K*. A number of different alternative values for each parameter are tested as $w = \{0.5, 2\}$; $c_1 = \{2, 5\}$; $c_2 = \{2, 5\}$;

Fig. 3. Improvement% of the algorithms results for A, B, M instances.

 r_1 ={0, 1}; r_2 = {0, 1}. Finally we set our best parameters as $w = 0.7$; $c_1 = c_2 = 2$; $r_1 = r_2 = 0.5$; $K = n/4$. We run the proposed hybrid PSO for each instance ten times with 100 iterations (i.e., algorithm termination criterion). The best result for each instance with average CPU time is obtained over ten runs. We observe that the improvement of results after 100 iterations is very marginal.

5.2. Performance evaluation of different algorithms

All the results in this study are evaluated by comparing the results reported by Battarra et al. [\[5\]](#page-11-9) using the branch and cut (BC) algorithm to solve the CluVRP problem. They could not achieve the optimal solutions for all the problem instances but reported the best feasible upper bound solutions obtained during the execution of their algorithms. The solutions by Battarra et al. [[5](#page-11-9)] are denoted by *UB*. Overall, the performance of the algorithms, including algorithms obtained from the literature, is evaluated by two criteria. The first criterion is that in how many instances does the algorithm finds a better solution than the upper bound, *UB* solution. It is reported in the tables under the ''No. of improved *UB*''. The second criterion is the improvement% of the algorithm compared to the *UB*. It is measured by Eq. [\(20\)](#page-6-2), where *Sol* is used to denote the solutions found by the other algorithms. The improvement% of a group instance is reported as ''improvement%'' in the tables. In addition, the processing time

(CPU time) is reported as t (s). The following formula is used to calculate improvement% from the *UB*.

$$
Improvement\% = \frac{UB - Sol}{UB} \times 100
$$
 (20)

[Tables](#page-7-0) [5](#page-7-0) and [6](#page-8-0) show all the results of this study including reported results from the literature.

In the performance evaluation, the statistical tests, nonparametric Friedman test and post-hoc Bonferroni test are used to check any significant difference exists in the performance of algorithms. Friedman's test only reveals the difference among the results of different algorithms. The Bonferroni test is performed after Friedman's test to show which particular pair of algorithms is different from each other in comparison [[46](#page-12-29)]. The statistical software IBM SPSS version 19 is used to run the Friedman and post-hoc Bonferroni test using $\alpha = 0.05$ as the level of significance.

5.2.1. Performance evaluation for A, B, M and P instances

[Table](#page-7-0) [5](#page-7-0) reports the results for the instances groups A, B, M, and P. The two-level VNS algorithm, decomposition-based method, two-level optimization, and the hybrid PSO are evaluated in the table. The comparison shows that all of the two-level VNS, the decomposition-based method, and the two-level optimization obtain the improved *UB* solution for one instance out of 75 instances; whereas, the hybrid PSO is capable of obtaining the

are less than the Bonferroni adjustment significant level 0.0125 and thus the null hypotheses are rejected. The rejection of the null hypotheses shows that the results of hybrid PSO are statistically different than the res We also performed post-hoc Bonferroni tests between algorithms
to check whether their results are statistically different or not. a significant statistical difference is found in comparing the perbased method, and two–level optimization, which shows that all the two–level VNS, the decomposition–based method, and two–level optimization are inferior to BC solutions. In the case of 1.04 he hybrid PSO solution, the o (from different, because the test of hybrid PSO and two-level VNS are not statistically significantly two-level optimization. The test further reveals that the results different than the results of the decomposition-based method and hypotheses shows that the results of hybrid PSO are statistically and thus the null hypotheses are rejected. The rejection of the null hybrid PSO and two-level optimization is 0.00007. These p values hybrid PSO and two-level optimization is 0.00007. These hybrid PSO and decomposition-based method is 0.0020; between *p* values hybrid PSO and decomposition-based method is 0.0020; between The p value of the pair-wise comparison Bonferroni test between We also performed post-hoc Bonferroni tests between algorithms
to check whether their results are statistically different or not.
The *p* value of the pair-wise comparison Bonferroni test between to check whether their results are statistically different or not. formance of hybrid PSO with all algorithms (p values PSO is 0.22 s, which is almost equal to the CPU time of the com-
petitive algorithm two-level VNS (0.23 s). In the Friedman test,
a significant statistical difference is found in comparing the per-
formance of hybrid PSO w formance of hybrid PSO with all algorithms (a significant statistical difference is found in comparing the perpetitive algorithm two-level VNS (0.23 s). In the Friedman test, by 1.12% (from (from hybrid PSO solution is superior to the two-level VNS by 0.08% 0.05% compared to the BC solution, which also indicates that the the hybrid PSO solution, the overall improvement is found to be level optimization are inferior to BC solutions. In the case of the two-level VNS, the decomposition-based method, and twoand addition, the overall improvements obtained are improved −1.7% respectively in the two-level VNS, decomposition- −5.00% to 0.05%), and to two-level optimization approach *UB* solution for a total of 2 instances out of 78. In −1.7% to 0.05%). The average CPU time of hybrid −0.03%, $= 0.000$ −5.00%, $\overline{8}$

rithms. The analysis also indicates that the proposed hybrid PSO decomposition-based method and two-level optimization algobe concluded that the proposed hybrid PSO is better than the is competitive with the two-level VNS for A, B, M, and P instances is competitive with the two-level VNS for A, B, M, and P instances. rithms. The analysis also indicates that the proposed hybrid PSO decomposition-based method and two-level optimization algobe concluded that the proposed hybrid PSO is better than the Based on the statistical test and average improvement%, it car Based on the statistical test and average improvement%, it can

tains negatively dispersed results from the UB for most of the from the omitted in nearest results to the results to the instances. instances. The algorithm, two-level VNS, achieves nearly closer tains negatively dispersed results from the [Fig.](#page-6-3) [3](#page-6-3) reveals that the two-level optimization algorithm ob-*UB* reveals that the two-level optimization algorithm ob-The algorithm, two-level VNS, achieves nearly closer [Fig.](#page-6-3) [3](#page-6-3) for the instances. *UB* because the results of the algorithm are far away but the proposed hybrid PSO achieves more *UB*. The decomposition-based method is for most of the

5.2.2. Performance evaluation for Golden instances *5.2.2. Performance evaluation for Golden instances*

Golden instances. two-level VNS algorithm obtain no improved *UB* solution of the the UHGS improves for 4 instances; whereas, the hybrid PSO
improves a total of 136 instances. The two-level algorithm and that the produced by the proposed PSO are found to be exceptionally $n = 360$ and 3 instances from group $n = 420$), because the results Golden instances. two-level VNS algorithm obtain no improved improves a total of 136 instances. The two-level algorithm and the UHGS improves for 4 instances; whereas, the hybrid PSO that the LMNS improves the in the appendix tables (better than other algorithms. Although we report all the results better than other algorithms. Although we report all the results produced by the proposed PSO are found to be exceptionally instances out of 220 instances (2 instances from instance group $n = 360$ and 3 instances from group $n = 420$), because the results $n = 360$ instances out of 220 instances (2 instances from instance group in the table. In the comparison study (in [Table](#page-8-1) 6), we omit in the table. In the comparison study (in two-level, two-level VNS, LMNS, and the hybrid PSO are evaluated two-level, two-level VNS, LMNS, and the hybrid PSO are evaluated includes a total of 220 instances. The results by the UHGS, the includes a total of 220 instances. The results by the UHGS, the [Table](#page-8-1) LMNS improves the *UB* solution for 114 instances [6](#page-8-1) reports the result for the Golden instances. This set [Tables](#page-9-1) 8 solution for 114 instances and to [14\)](#page-11-18). The comparison shows solution of the [6](#page-8-1)), we omit 5 pue ŪΙ

 \overline{a} server with four 2.1 GHz processors with 16-core each and a total competitor is LMNS of 256 GB of RAM. The UHGS uses a Xeon CPU with 3.07 GHz server with four 2.1 GHz processors with 16-core each and a total for the hybrid PSO is 9.44 s only. The hybrid PSO uses a Linux for the hybrid PSO is 9.44 s only. The hybrid PSO uses a Linux UHGS is as 9.5 s and 626.70 s respectively; whereas, the CPU time UHGS is as 9.5 s and 626.70 s respectively; whereas, the CPU time competitor is LMNS and UHGS. The CPU time for the LMNS and existing algorithms. In terms of solution quality, our nearest overall average improvement of 0.40%, which is better than all −LMNS, UHGS, the two-level, two-level VNS is [256 2.40%, and The overall average improvement for Golden instances using GB of RAM. The −1.08% respectively. The hybrid PSO obtains an and UHGS. The CPU time for the LMNS **UHCS** uses a Xeon CPU with −0.18%, 3.07 −0.03%, ZH₃ pue

Table 5Summarized results of A, B, M, and P instances.

Two-level VNS Instances in BC			Decomposition-based method		Two-level optimization		Hybrid PSO							
Group	No. of instances	No. of Customer	No. of improved UB	Improvement	t(s)	No. of improved UB	Improvement	t (s)	No. of improved UB	Improvement	t(s)	No. of improved UB	Improvement	t(s)
A	27	$31 - 79$	0/24	$-0.07%$	0.05		$-2.6%$	\cdots		$-1.21%$	\cdots	0	0.00%	0.06
B	23	$30 - 77$	0	$-0.03%$	0.04	Ω	$-3.0%$	\cdots		$-1.63%$	\cdots		0.00%	0.04
M		$100 - 261$		0.11%	3.48	0	$-32.3%$	\cdots	0	$-5.32%$	\cdots		0.09%	2.09
	24	$15 - 100$	Ω	$-0.01%$	0.07	\cdots	\cdots	\cdots	\cdots	\cdots	\cdots		0.13%	0.27
Total	78	\cdots	1/75	\cdots	\cdots	1/78	\cdots	\cdots	1/78	\cdots	\cdots	2/78	\cdots	\cdots
Avg	\cdots	\cdots	\cdots	$-0.03%$	0.23	\cdots	$-5.00%$	\cdots	\cdots	$-1.7%$	\cdots	\cdots	0.05%	0.22

here in terms of both solution quality and CPU time. concluded that the hybrid PSO is superior to all algorithms stated of speed, these computers are comparable. Therefore, it can be 3.5 GHz with 64 GB RAM to perform their computations. In terms MS Windows 7 with an Intel(R) Core(TM) i7- 5930K CPU with with 16 GB of RAM, and LMNS uses a personal computer with level VNS uses CPU with Intel(R) Core(TM) i7-4790 with 3.60 GHz with 16 GB of RAM running under Oracle Linux Server 6.4, two-

The statistical analysis reveals that there are significant difall algorithms in the Friedman test ferences in the comparison of the performance of hybrid PSO to *(p* v*alues* = 0 .000*).* The pairthe results of these two algorithms are not statistically different. between hybrid PSO and two-level VNS algorithms shows that different than the results of UHGS, two-level, and LMNS. The test wise Bonferroni test shows that the results of PSO are statistically

Based on the statistical test and average improvement%, it two-level VNS for the Golden instances. indicates that the proposed hybrid PSO is competitive with the the UHGS, two-level, and LMNS algorithms. The analysis also can be concluded that the proposed hybrid PSO is better than

As it can be noted from be noted from [Fig.](#page-9-2) 4, the hybrid [4](#page-9-2), the hybrid PSO improves the results nearly close to the results but not as good as UHGS algorithm results. The UHGS finds algorithm. The LMNS algorithm generates comparatively better obtains relatively worse results followed by the two-level VNS the solution for most instances group. The two-level algorithm results but not as good as UHGS algorithm results. The UHGS
the results nearly close to the *UB* for most of the instances for most of the instances.

formance 5.2.3. Effect of hybridizing and improvement scheme on PSO's per-

The effect of hybridizing the proposed PSO on solution quality is presented in is presented in [Table](#page-9-3) [7.](#page-9-3) The performance of the hybridization of are the same for all settings. computational time. All other parameters in the PSO framework each setting is changed to maintain approximately the same and with improvement scheme). The number of iterations for improvement scheme; and the proposed PSO (i.e., PSO with VNS and without improvement scheme; PSO with VNS and without a total of 298 instances under three settings: PSO without VNS the PSO is evaluated for the 20 major customers groups with

[Table](#page-9-3) [7](#page-9-3) shows that hybridizing the PSO with VNS and without shows that hybridizing the PSO with VNS and without − 83.59% to without VNS and without improvement scheme by 82.54% (from improvement scheme improves the solution quality of the PSO −1.05%). The solution quality of the PSO with VNS (from and without improvement scheme is further improved by 1.06% −1.05% to 0.01%) by hybridizing the PSO with VNS and scheme in PSO. the PSO with the VNS and with the inclusion of the improvement improvement scheme. These results justify the hybridization of mance of PSO is enhanced if hybridization with VNS and with improvement scheme. Thus, the table denotes that the perfor-

In the pure improvement scheme, we implement the improve- (ILS) [7,47]. The result of the pure improvement scheme is found scheme without PSO can be considered as an iterative local search number of iterations is reached. Thus, the pure improvement are implemented. The process is repeated until the specified is perturbed, and then local searches of the improvement scheme specified number of iterations. In this scheme, the initial solution ment scheme on the randomly generated initial solution for a specified number of iterations. In this scheme, the initial solution is forturbed, and then local searches of the improvement scheme are implemented. The process as the improvement% of 0.01% and it improves the *UB* solution efficient ILS for solving the clustered vehicle routing problem. the potential of ILS. A further investigation is needed to design an PSO algorithm. This observation brings an interesting fact about The result of the improvement scheme is close to the proposed 0.01% to 0.31%) superior to the pure improvement scheme result. PSO is found as the improvement% of 0.31%, which is 0.30% (from pure improvement are 14,000. The result of the proposed hybrid for 94 instances with CPU time of 9.67 s. The total iterations for

Fig. 4. Improvement% of the algorithms results for 16 groups of Golden instances.

 \overline{a} \overline{a}

Table 8

Table 9 Results for the instances M, P.

6. Conclusion

The combinatorial optimization problem, the CluVRP, is considered in this paper. In the CluVRP, customers are partitioned into predefined clusters. The same vehicle is assigned to serve all customers consecutively under a cluster before it moves to another cluster or returns to the depot. All customers and clusters must be served only once. The objective of the problem is to find the optimal distribution costs for the logistic network serving all customers by using the available vehicles. In this paper, a hybrid PSO algorithm is proposed to solve the CluVRP. With the complementary nature of both algorithms, the hybrid PSO combines the local optimal improvement capabilities of VNS with the swarm based diversification abilities of the PSO. The

Results for the Golden instances 1–4.

Instance				BC	Hybrid PSO		
Group	n	с	m	UB	Solution	CPU t(s)	Improvement %
Golden 1	240	17	4	4831	4751	3.66	1.66%
Golden 1	240	18	$\overline{4}$	4847	4757	2.42	1.86%
Golden 1	240	19	$\overline{4}$	4872	4789	2.45	1.70%
Golden 1	240	21	$\overline{4}$	4889	4790	2.57	2.02%
Golden 1	240	22	4	4908	4826	2.58	1.67%
Golden 1	240	25	$\overline{4}$	4899	4818	2.61	1.65%
Golden 1	240	27	$\overline{4}$	4934	4862	2.60	1.46%
Golden 1	240	31	$\overline{4}$	5050	4953	2.68	1.92%
Golden 1	240	35	$\overline{4}$	5102	5047	2.98	1.08%
Golden 1	240	41	$\overline{4}$	5097	5058	3.64	0.77%
Golden 1	240	49	3	5000	4953	4.38	0.94%
Golden 2	320	22	$\overline{\mathbf{4}}$	7716	7622	6.10	1.22%
Golden 2	320	23	$\overline{4}$	7693	7578	6.04	1.49%
Golden 2	320	25	$\overline{4}$	7668	7571	6.14	1.26%
Golden 2	320	27	4	7638	7527	5.27	1.45%
Golden 2	320	30	$\overline{4}$	7617	7552	4.55	0.85%
Golden 2	320	33	4	7640	7548	4.12	1.20%
Golden 2	320	36	$\overline{4}$	7643	7550	4.71	1.22%
Golden 2	320	41	$\overline{4}$	7738	7644	4.80	1.21%
Golden 2	320	46	$\overline{4}$	7861	7795	5.59	0.84%
Golden 2	320	54	$\overline{4}$	7920	7830	7.27	1.14%
Golden 2	320	65	$\overline{4}$	7892	7841	10.32	0.65%
Golden 3	400	27	$\overline{4}$	10540	10489	17.15	0.48%
Golden 3	400	29	$\overline{4}$	10504	10393	11.23	1.06%
Golden 3	400	31	$\overline{4}$	10486	10395	8.33	0.87%
Golden 3	400	34	4	10465	10408	8.56	0.54%
Golden 3	400	37	$\overline{4}$	10482	10415	8.50	0.64%
Golden 3	400	41	$\overline{4}$	10501	10426	10.03	0.71%
Golden 3	400	45	$\overline{4}$	10485	10405	9.66	0.76%
Golden 3	400	51	$\overline{4}$	10583	10538	10.70	0.43%
Golden 3	400	58	$\overline{4}$	10776	10751	12.38	0.23%
Golden 3	400	67	4	10797	10785	15.36	0.11%
Golden 3	400	81	$\overline{4}$	10614	10627	22.75	$-0.12%$
Golden 4	480	33	$\overline{4}$	13598	13567	19.24	0.23%
Golden 4	480	35	$\overline{4}$	13643	13635	19.17	0.06%
Golden 4	480	37	$\overline{4}$	13520	13498	16.29	0.16%
Golden 4	480	41	$\overline{4}$	13460	13473	16.55	$-0.10%$
Golden 4	480	44	$\overline{4}$	13568	13540	16.65	0.21%
Golden 4	480	49	$\overline{4}$	13758	13772	17.88	-0.10%
Golden 4	480	54	4	13760	13767	19.11	$-0.05%$
Golden 4	480	61	4	13791	13796	20.86	$-0.04%$
Golden 4	480	69	4	13966	13975	20.77	$-0.06%$
Golden 4	480	81	4	13975	14001	27.50	$-0.19%$
Golden 4	480	97	$\overline{4}$	13775	13833	36.26	$-0.42%$

Table 11

Results for the Golden instances 5–8.

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Table 12

Results for the Golden instances 17–20.

algorithm is tested on the benchmark instances found in CluVRP literature. The major contributions of the study include designing a new hybrid PSO metaheuristic algorithm to solve the CluVRP and finding the new best-known solutions for a total of 138 instances out of 293 benchmark instances with an average CPU time of 6.99 s. It is also contributed in this study by adding new features in the PSO algorithm such as the use of two types of particles and improvement scheme for the personal best solution. In the improvement scheme, the personal best solutions of the swarm are further improved by adopting the perturbation and VNS method. Hence, the proposed algorithm has great potential for solving instances of other variants of VRP. With the capability of a quality solution on relatively acceptable CPU time, the algorithm has the perspective to use in many practical scenarios such as distribution logistics with $CO₂$ emission cap leading to a penalty, the problem of perishable items, and transportation problems in military operations, etc. Like all research works, this work also has some limitations and future research directions. Many attributes of VRPs such as time windows, carbon emissions, backhaul, and multi-depot can be added with CluVRP to capture real-world scenarios. Although the proposed algorithm is designed to solve CluVRP solely, it can be easily extended to solve other variants of VRP. Future research works can also explore the possibility of combining PSO with other metaheuristics such as genetic algorithm, tabu search, simulated annealing etc.

CRediT authorship contribution statement

Md. Anisul Islam: Analyzed the problem, Designed the methodology, Analyzed and interpreted the data, Conceptualized the solution techniques, Performed the experiments, Wrote the

paper. **Yuvraj Gajpal:** Designed the methodology, Analyzed and interpreted the data, Conceptualized the solution techniques, Reviewed and edited the paper. **Tarek Y. ElMekkawy:** Designed the methodology, Analyzed and interpreted the data, Conceptualized the solution techniques, Reviewed and edited the paper.

Declaration of competing interest

The authors declare that they have no known competing financial interests or personal relationships that could have appeared to influence the work reported in this paper.

Acknowledgments

The authors acknowledge the funding received from the Manitoba Government through the Department of Education and Advanced Learning, and the University of Manitoba to support this research. The authors thank the anonymous referees for their valuable comments.

Appendix. The detailed computational results

See [Tables](#page-9-4) [8](#page-9-4)[–14.](#page-11-20)

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