ANALYSIS OF THE COUPLING GAP BETWEEN MICROSTRIP ANTENNAS

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ABSTRACT

The accurate and efficient Galerkin's method was developed in the spectral domain for analyzing gap discontinuities in patch antenna array. Using new current distribution the problem is solved using full wave approach rather than quasi-static approximation. The new current distribution speeds up the convergence of the solution for obtaining the resonance frequency of the system with electric and magnetic walls at the planes of symmetry. The equivalent circuit of the gap is determined for different gap sizes.

Keywords: Microstrip, Patch antenna, Coupled arrays, Microstrip resonator, Coupling gap.

INTRODUCTION

One of the effective methods for increasing the bandwidth of patch antenna is to add two resonators which are coupled to the patch radiating edges [1]. The coupling gap between the two opened rectangular patches were modeled as two dimensional capacitive networks as shown in Fig. 1. The values of these capacitance’s are obtained using formulas given in reference [2] for even and odd modes of coupled microstrips of unequal widths. Complete characterization of the gap is presented in this paper. Galerkin’s technique is applied in the spectral domain to solve the microstrip resonators problem. The characteristic equations for resonant frequencies are derived for both electric and magnetic walls at the planes of structure symmetry. The new current distribution basis functions which are transformed into Bessel functions in the spectral domain, reduces computational time with good accuracy.
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two electric or magnetic walls

![Diagram of patch array with labels](image)

(a)

![Diagram of gap equivalent circuit](image)

(b)

Fig. 1. Patch array: (a) Gap coupled resonators, (b) Gap equivalent circuit

ANALYSIS OF MICROSTRIP RESONATOR

The fields existing in the structure are obtained from the superposition of TE and TM fields. They can be expressed in terms of two scalar potentials $e(x, y, z)$ and $h(x, y, z)$ as follows:

$$ E_{zi}(x,y,z) = k_1^2 e_i + \frac{\partial^2 e_i}{\partial z^2} \quad (1-a) $$

$$ H_{zi}(x,y,z) = k_1^2 h_i + \frac{\partial^2 h_i}{\partial z^2} \quad (1-b) $$
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\[ E_{xi}(x, y, z) = \frac{\partial^2 e_i}{\partial x \partial z} - j \omega \mu_i \left( \frac{\partial h_i}{\partial y} \right) \]  
\[ H_{xi}(x, y, z) = \frac{\partial^2 h_i}{\partial x \partial z} + j \omega \varepsilon_i \left( \frac{\partial e_i}{\partial y} \right) \]

where \( i = 1 \) or \( 2 \), designates the substrate or air region.

\[ \varepsilon_1 = \varepsilon_0 \varepsilon_r, \varepsilon_2 = \varepsilon_0, \mu_1 = \mu_0 \mu_r, \mu_2 = \mu_0 \]

The field components are transformed into the spectral domain using Fourier transforms

\[ e_i(\alpha, y, \beta) = \int_{-\infty}^{\infty} dz \int_{-\infty}^{\infty} dx e_i(x, y, z) \exp(j\alpha x) \exp(j\beta z) \]  
\[ h_i(\alpha, y, \beta) = \int_{-\infty}^{\infty} dz \int_{-\infty}^{\infty} dx h_i(x, y, z) \exp(j\alpha x) \exp(j\beta z) \]

where \( \alpha \) and \( \beta \) are Fourier transform variables. The boundary conditions [3] are transformed and applied to the Fourier transforms of the field equations (1-a) to (1-d) to obtain the solutions of field components in Fourier domain as follows:

\[ e_1(\alpha, y, \beta) = A(\alpha, \beta) \text{Sinh}(\gamma_1 y) \]  
\[ h_1(\alpha, y, \beta) = B(\alpha, \beta) \text{Cosh}(\gamma_1 y) \]  
\[ e_2(\alpha, y, \beta) = C(\alpha, \beta) \exp[-\gamma_2(y - d)] \]  
\[ h_2(\alpha, y, \beta) = D(\alpha, \beta) \exp[-\gamma_2(y - d)] \]

A, B, C, D are unknowns which are obtained from applying the continuity conditions at the interface \( y = d \) in the spectral domain [3]. The coefficients are expressed in terms of the unknown strip currents \( J_x(x, z) \) and \( J_z(x, z) \).

The final boundary condition is:

\[ E_x(x, d, z) = E_z(x, d, z) = 0 \quad |x| < W, |z| < L \]

while \( E_x(x, d, z) \) and \( E_z(x, d, z) \) have different values in the dielectric regions.

This condition is applied in the spectral domain to eliminate the unknown coefficients and obtain the following coupled equations:
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\[ E_x(\alpha, \beta) = U_1(\alpha, \beta)\tilde{J}_x(\alpha, \beta) + U_2(\alpha, \beta)\tilde{J}_z(\alpha, \beta) \quad (5-a) \]

\[ E_z(\alpha, \beta) = U_3(\alpha, \beta)\tilde{J}_x(\alpha, \beta) + U_4(\alpha, \beta)\tilde{J}_z(\alpha, \beta) \quad (5-b) \]

where \( U_1, \ U_2, \ U_3 \) and \( U_4 \) are the Fourier transform of the Green's functions, \( \tilde{J}_x \) and \( \tilde{J}_z \) are the Fourier transforms of the unknown patch currents.

**CURRENT DISTRIBUTION FUNCTIONS**

Accurate knowledge of \( x \) and \( z \) components of patch current distributions helps in accurate evaluation of patch dispersion characteristics. The choice of the basis functions is very important in problem convergence and computational time. In this work a new current distribution function is assumed in the form:

\[ J_x(x, z) = \sum_{n=0}^{\infty} A_n X_n(x, z) \quad (6-a) \]

\[ J_z(x, z) = \sum_{n=0}^{\infty} B_n Z_n(x, z) \quad (6-b) \]

Where \( A_n \) and \( B_n \) are unknown coefficients to be solved and the basis \( X_n \) and \( Z_n \) has the forms:

\[ X_n(x, z) = \frac{-j\sin(n+1)Q \cdot -j\sin(n\bar{Q})}{(n+1)\pi W \cdot \left(L^2 - z^2\right)^{\frac{1}{2}}} - (7-a) \]

\[ Z_n(x, z) = \frac{\cos(nQ) \cdot \cos(n+1)\bar{Q}}{\left(W^2 - x^2\right)^{\frac{1}{2}} \cdot (n+1)\pi L} \quad (7-b) \]

where \( Q = \arcsin(x/W), \ \bar{Q} = \arcsin(z/L) \)

The Fourier transforms of (6) are given by:
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\[ \tilde{J}_x(\alpha, \beta) = \sum_{n=0}^{\infty} A_n \frac{J_{n+1}(\alpha W)}{\alpha W} J_n(\beta L) \quad (n \text{ odd}) \]  
\[ \tilde{J}_z(\alpha, \beta) = \sum_{n=0}^{\infty} B_n J_n(\alpha W) \frac{J_{n+1}(\beta L)}{\beta L} \quad (n \text{ even}) \]  

where \( J_n(\alpha W) \) and \( J_n(\beta L) \) are Bessel functions.

**PATCH RESONANCE FREQUENCY**

Substituting equation (8) into equation (5) and taking the inner products with the basis functions \( X_i \) and \( Z_i \) for different values of \( i \), one applies Parseval’s relations to obtain the matrix equations:

\[ \sum_{m=0}^{\infty} A_m F_{im} + \sum_{n=0}^{\infty} B_n G_{in} = 0 \quad (m, i \text{ odd}), (n \text{ even}) \]  
\[ \sum_{m=0}^{\infty} A_m H_{im} + \sum_{n=0}^{\infty} B_n K_{in} = 0 \quad (n, i \text{ even}), (m \text{ odd}) \]  

where

\[ F_{im} = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} U_1 \frac{J_{m+1}(\alpha W)}{\alpha W} J_m(\beta L) \bar{X}_i(\alpha, \beta) \, d\alpha \, d\beta \]  
\[ G_{in} = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} U_2 \frac{J_{n+1}(\beta L)}{\beta L} J_n(\alpha \beta) \bar{X}_i(\alpha, \beta) \, d\alpha \, d\beta \]  
\[ H_{im} = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} U_3 \frac{J_{m+1}(\alpha W)}{\alpha W} J_m(\beta L) \bar{Z}_i(\alpha, \beta) \, d\alpha \, d\beta \]  
\[ K_{in} = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} U_2 \frac{J_{n+1}(\beta L)}{\beta L} J_n(\alpha W) \bar{Z}_i(\alpha, \beta) \, d\alpha \, d\beta \]

The determinant of the coefficient matrix must be equal to zero for a certain value of complex frequency \( f \). The values of \( m, n \) and \( i \) must be truncated.
ANALYSIS OF THE GAP IN PATCH ARRAY

Gap parameters are obtained using the same analysis of the patch with additional two electric and magnetic walls placed at the planes of symmetry as shown in Fig. 1. When walls are used the modes in the x-direction will be discrete rather than continuous modes existing in open structures. So the transformation in x-direction will be discrete Fourier variable $\eta_k$ depending on the kind of walls as follows [3]:

For electric walls

$$\eta_k = (k - 1/2)\pi/s$$ for $E_z$ even $- H_z$ odd (in x) modes

$$\eta_k = k\pi/s$$ for $E_z$ odd $- H_z$ even (in x) modes

(11-a) (11-b)

For magnetic walls

$$\eta_k = k\pi/s$$ for $E_z$ even $- H_z$ odd (in x)

$$\eta_k = (k - 1/2)\pi/s$$ for $E_z$ odd $- H_z$ even (in x)

(11-c) (11-d)

where $k = 1, 2, 3, ...$

The new resonance frequency corresponding to electric wall structure is $f_e$ and that for magnetic wall is $f_m$. The corresponding wave lengths are:

$$\lambda_e = C / f_e (\varepsilon_{re})^{1/2}$$

$$\lambda_m = C / f_m (\varepsilon_{re})^{1/2}$$

(12-a) (12-b)

where $C$ is the free space velocity of light, $\varepsilon_{re}$ is the effective dielectric constant given in reference [4] for dispersive behavior of microstrips.

EQUIVALENT CIRCUIT OF THE GAP

Open-ended gap in microstrip patches are represented by an extension in the patch length $\Delta l_e$ for electric walls and $\Delta l_m$ for magnetic walls where:
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\[ \Delta l_e = \left( \frac{\lambda_e}{2} - 2L \right) / 2 \]  
\[ \Delta l_m = \left( \frac{\lambda_m}{2} - 2L \right) / 2 \]  

The equivalent capacitance's [5] are given by:

\[ C_e = \Delta l_e \left( \varepsilon_{re} \right)^{1/2} / C Z_0 \]  
\[ C_m = \Delta l_m \left( \varepsilon_{re} \right)^{1/2} / C Z_0 \]

where \( Z_0 \) is the characteristic impedance[4]. [6] \( C_e \) and \( C_m \) are related to the \( \pi \)-circuit of the gap by the equations:

\[ C_g = (C_e - C_m) / 2 \]  
\[ C_p = C_m \]

**NUMERICAL RESULTS AND CONCLUSION**

The complex resonance frequencies at both electric and magnetic walls are computed to evaluate the equivalent \( \pi \)-network of the coupling gap. The imaginary part of the frequency represents the radiation losses from the fringing fields at the patch ends. The series capacitance \( C_g \) (Fig. 2) increases as the gap decreases which agree with the capacitor basic idea. Capacitance \( C_p \) is negative because the gap reduces the overall microstrip shunt capacitance in the vicinity of the symmetrical plane. The new current distribution reduces the computational time due to the fast problem convergence. The matrix size is increased to (6x6) to obtain satisfactory results, truncation error is less than 5% compared to experimental work in reference [1]. The method is effective in solving antenna arrays and other complicated structures. Tables 1 and 2 show some results for different Teflon substrates with dielectric constant \( \varepsilon_r = 2.2 \) and \( d = 0.17 \) cm and substrates having \( \varepsilon_r = 2.55 \) and \( d = 0.159 \) cm.
Table 1. Gap Parameters for \( \epsilon_r = 2.2 \), \( d = 0.17 \) cm, \( 2W = 3.95 \) cm.

<table>
<thead>
<tr>
<th>Spacing (2S) cm</th>
<th>0.15</th>
<th>0.19</th>
</tr>
</thead>
<tbody>
<tr>
<td>( f_e ) GHz</td>
<td>( 3.731 + j 0.75 \times 10^{-4} )</td>
<td>( 2.877 + j 0.24 \times 10^{-6} )</td>
</tr>
<tr>
<td>( f_m ) GHz</td>
<td>( 5.235 + j 0.125 \times 10^{-6} )</td>
<td>( 5.257 + j 0.177 \times 10^{-5} )</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Spacing (2L) cm</th>
<th>0.15</th>
<th>0.19</th>
</tr>
</thead>
<tbody>
<tr>
<td>( f_e ) GHz</td>
<td>( 3.722 + j 0.118 \times 10^{-3} )</td>
<td>( 3.599 + j 0.559 \times 10^{-6} )</td>
</tr>
<tr>
<td>( f_m ) GHz</td>
<td>( 5.201 + j 0.611 \times 10^{-5} )</td>
<td>( 5.242 + j 0.539 \times 10^{-8} )</td>
</tr>
</tbody>
</table>

Table 2. Gap Parameters \( \epsilon_r = 2.55 \), \( d = 0.159 \) cm, \( 2W = 3.95 \) cm, \( 2L = 2.71 \) cm

<table>
<thead>
<tr>
<th>Spacing (cm)</th>
<th>0.15</th>
<th>0.17</th>
<th>0.19</th>
<th>0.2</th>
</tr>
</thead>
<tbody>
<tr>
<td>( f_e ) GHz</td>
<td>( 4.797 - j 0.24 \times 10^{-6} )</td>
<td>( 4.799 - j 0.29 \times 10^{-6} )</td>
<td>( 4.841 - j 0.901 \times 10^{-6} )</td>
<td>( 4.849 - j 0.409 \times 10^{-6} )</td>
</tr>
<tr>
<td>( f_m ) GHz</td>
<td>( 5.001 - j 0.909 \times 10^{-8} )</td>
<td>( 4.99 - j 0.158 \times 10^{-7} )</td>
<td>( 4.98 - j 0.232 \times 10^{-7} )</td>
<td>( 4.899 - j 0.281 \times 10^{-7} )</td>
</tr>
<tr>
<td>( C_g ) (Pf)</td>
<td>0.0885</td>
<td>0.0843</td>
<td>0.0802</td>
<td>0.07151</td>
</tr>
<tr>
<td>( C_p ) (Pf)</td>
<td>-2.2895</td>
<td>-2.2831</td>
<td>-2.2764</td>
<td>-2.2822</td>
</tr>
</tbody>
</table>
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Fig. 2. $C_g$ and $-C_p$ versus spacing for different patch lengths

REFERENCES


