

Graduate Students

OPTIMIZATION MODELS FOR MULTIPLE RESOURCE PLANNING

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Abstract

- Multiple Resource Planning (MRP) is a very crucial undertaking for most organizations.
- MRLPs are very prevalent in today's organizational environments and are particularly critical for organizations that handle concurrent, time-intensive, and multiple-resource projects.
- MRP facilitates efficient allocation of resources and reduces costs.
- Using data obtained from the Ministry of Administrative Development, Labour and Social Affairs (ADLSA), an MRLP is proposed.
- A novel models and solution approach for the MRLP were proposed.
- The results show that the model performs well, even in higher instances.
- The positive results attest to the effectiveness of the proposed MRLP problem.

Introduction/Objectives

Create a solution that solves the key challenges that project managers encounter in day-to-day management of multiple projects.

Dealing with high project demands, uncertainties, project constraints, and dealing with competing priorities.

Enhance project scheduling within a given time horizon to get the optimal resource allocation solution.

Methods and Materials

*Input Data:

- n : Number of tasks,
- R : Number of resources,
- H : Time horizon,
- b_{rt} : Capacity of resource r at period t ,
- m_j : Number of execution modes of task j ,
- a_{jrk} : Consumption of resource r by task j under mode k ,
- p_j : Processing time of task j under mode k ,
- r_j : start date of the project
- d_j : Due date of task j ,
- w_j : Weight of task j ,
- σ_{rt} : Cost of adding one unit of capacity to resource r at period t .

*Decision Variables:

- x_{jk} : Binary variable that takes value 1 if task j is executed under mode k , and 0 otherwise.
- y_{jt} : Binary variable that takes value 1 if task j is executed during period t , and 0 otherwise.
- s_{jt} : Binary variable that takes value 1 if task j starts at the beginning of period t , and 0 otherwise (that means, $s_{jt} = 1 \Rightarrow$ task j starts at time t).
- f_{jt} : Binary variable that takes value 1 if task j finishes at the end of period t , and 0 otherwise (that means, $f_{jt} = 1 \Rightarrow$ task j finishes at time $t+1$).
- T_j : Tardiness of task j .
- z_{rt} : Additional capacity of resource r at period t .

*Test Instances Ranges:

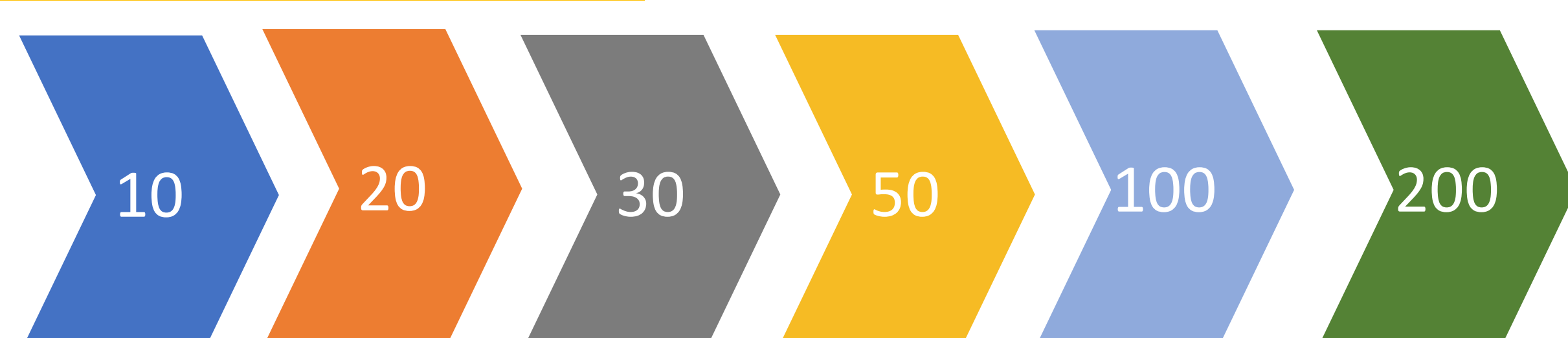


Figure 1. Number of projects ranges

Model Formulation

Model (MM, MR, FC): Minimize $\sum_{j=1}^n w_j T_j + \sum_{r=1}^R \sum_{t=1}^H \sigma_{rt} z_{rt}$

Subject to:

$$\sum_{k=1}^{m_j} x_{jk} = 1, \quad j = 1, \dots, n$$

$$\sum_{t=1}^H s_{jt} = 1, \quad j = 1, \dots, n$$

$$\sum_{t=1}^H f_{jt} = 1, \quad j = 1, \dots, n$$

$$\sum_{t=1}^H t s_{jt} \geq r_j, \quad j = 1, \dots, n$$

$$\sum_{t=1}^H t s_{jt} + \sum_{k=1}^{m_j} p_{jk} x_{jk} = \sum_{t=1}^H t f_{jt}, \quad j = 1, \dots, n$$

$$\sum_{t=1}^H s_{jt} - \sum_{t=1}^H f_{jt} = y_{jt}, \quad j = 1, \dots, n; t = 1, \dots, H$$

$$\sum_{j=1}^n \sum_{k=1}^{m_j} a_{jrk} u_{jkt} \leq b_{rt} + z_{rt} \quad r = 1, \dots, R; t = 1, \dots, H$$

$$T_j \geq \sum_{t=1}^H t f_{jt} - d_j, \quad j = 1, \dots, n$$

$$x_{jk} + y_{jt} \leq u_{jkt} + 1, \quad j = 1, \dots, n; R = 1, \dots, m_j; t = 1, \dots, H$$

x, y, z binary,
 $T, s, f, u \geq 0$,

Results & Discussion

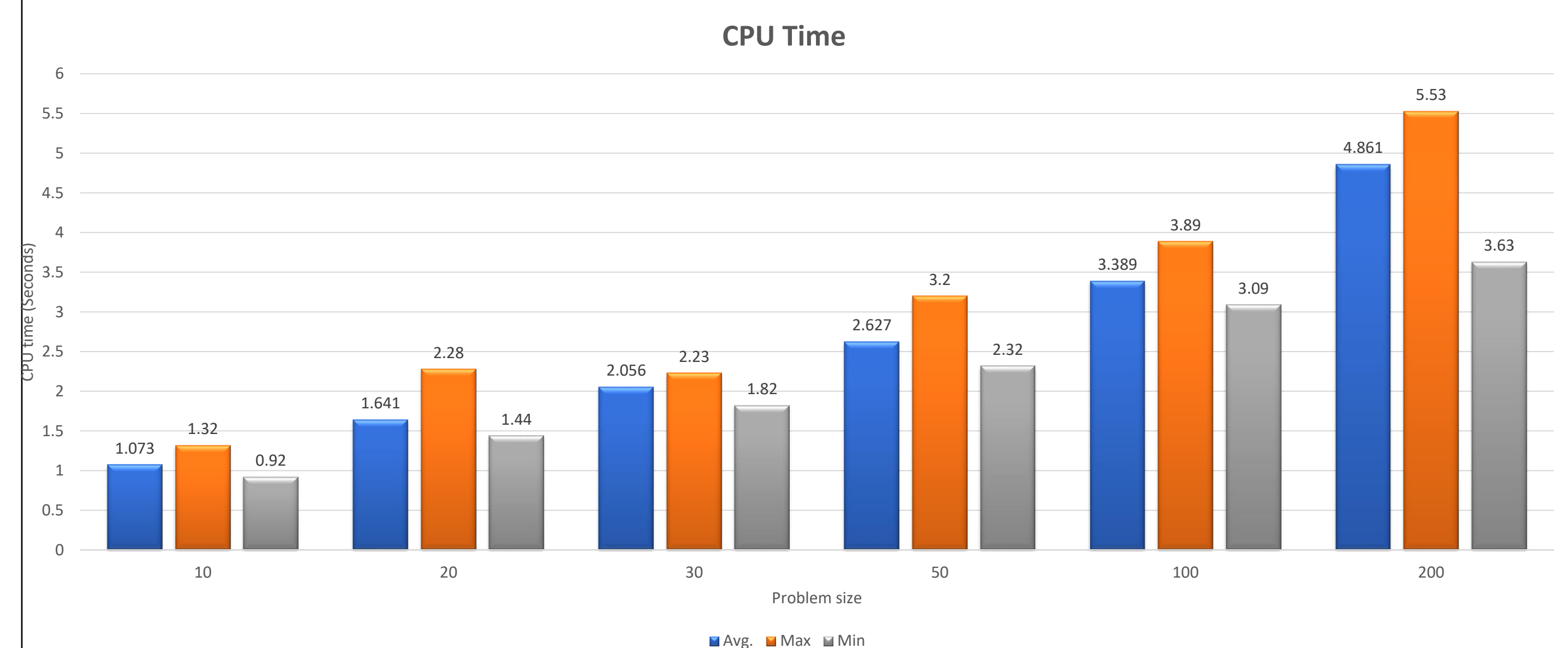


Figure 2. CPU time of the model

- As the complexity of the test instances increased, the CPU time has increased reasonably. The proposed model was performed within a very short time (seconds) even when increasing complexity of tasks number to 200.
- The maximum running time was completed in 5.53 seconds while the average time-solving time is between 1.073 and 4.861 seconds.

Conclusions

Provides a solution that minimizes time wastages and ensures efficient resource utilization for both single-mode and multi modes projects, while allows the combination of resources while considering restrictions and time constraints to achieve optimal scheduling and resource planning.

References

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