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On designing a sequential based EWMA structure for efficient process monitoring

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ABSTRACT

Control chart is a popular technique that is widely used in statistical process control to identify any possible deviations from a stable state of a process. Shewhart charts are famous for identifying larger shifts, while cumulative sum and exponentially weighted moving average control charts are well known for identifying smaller shifts in process parameters. This study examines the performance of a sequential-based EWMA (namely SEWMA_β) chart for observing the location of a normally distributed process. The performance of SEWMA_β is observed by using several overall run length properties (like average, median and standard deviation). The comparative study reveals that the overall performance of the proposed design is better than the existing counterparts. Moreover, the superiority depends on the choice of the design parameters of the proposed chart. A real-life data set from a steel rod manufacturing industry were considered to show the real-life illustration of the proposed design.

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Average run length; control charts; exponentially weighted moving average; sequential approach; manufacturing processes

1. Introduction

Statistical process control (SPC) is a mechanism that helps in monitoring the stability of an ongoing process to produce quality products. It comprises extremely powerful tools such as pareto chart, cause and effect diagram, fishbone diagram, flow diagram and control chart (cf. Montgomery [1]). SPC is vital for the reputation of a manufacturing industry that relies on the quality of products in a global market competition. Within the SPC toolkit, control charts are the most important tools used for observing and detecting the special cause variations and ultimately enhancing the performance of the product (cf. Shewhart [2]). In order to monitor any ongoing process, the use of appropriate control charting techniques is essential to ensure the stability of the process and to provide several benefits such as reduction in cost and time and increase in efficiency of the industrial process. Shewhart charts are well known for the detection of large shifts in process parameters while exponentially weighted moving average (EWMA) (cf. Roberts [3]) and cumulative sum (CUSUM) charts (cf. Page [4]) are mostly used for the detection of small to moderate shifts. In this study, we introduce an efficient sequential-based EWMA chart which is more sensitive to shifts in process location. Several authors worked to enhance the performance of classical EWMA chart (cf. Yang et al. [5]). The aim of this article is to design an EWMA chart based on a sequential testing algorithm to enhance the performance of the traditional EWMA chart and to increase its efficiency over the classical setup.

In the existing literature, there are mainly two forms of charts where sequential process monitoring is used. That is, some SPC practitioners adopt sequential sampling in their study, while others implement SPRT control charts for online monitoring. Both approaches have an advantageous mechanism for quality control charts for the monitoring of process parameters. According to Matheson [6], the probability of identifying the shift using sequential sampling is more than or equivalent to the likelihood of identifying the shift using a random sampling technique in-control charts as it needs fewer number of samples at a smaller cost. Green [7] highlighted that there is little advantage to sequential sampling if the cost of sample collection is similar to the cost of sample analysis. That is, if sequential sampling is to be more economical than many used approaches, less time should be needed to take a sample in the field than to analyse it in the laboratory. Sequential sampling is appropriate when the time required to gather at least one observation is a very small interval. In this way, it is likely to take numerous samples successively at a sampling point. A useful discussion in this context may be seen in Green [8] and the references therein. As a natural extension of the ideas from sequential analysis, sequential sampling methods have been widely used in the area of acceptance sampling but not so much in process monitoring (cf. Stoumbos and Reynolds [9, 10]).

The sequential probability ratio test (SPRT) chart is useful where testing is very costly or difficult. Peng and Reynolds [11] applied sequential sampling using gen-

eralized likelihood ratio (GLR) charts. Steiner et al. [12] designed the exact expression for the Wald-SPRT and CUSUM design. Various authors also worked on single directional process monitoring using sequential sampling (SS). Reynolds [13–15] and Reynolds et al. [16, 17] designed sequential sampling-based control charts which were very effective for detecting changes in a single direction in the process, with some tuning parameters specified. Reynolds and Arnold [18] constructed a one-sided EWMA design for VSI following a sequential sampling algorithm. Zhang et al. [19] designed an EWMA chart under a sequential sampling scheme for single directional process monitoring, and this design was more sensitive to single direction shift detection in the process. Stoumbos and Reynolds [20] designed SPRT chart for process location which was more efficient and highly effective with administrative benefits. Ou et al. [21] designed an SPRT location chart using several sampling intervals. Ou et al. [22] further enhanced the performance of SPRT location chart. Xu and Jeske [23] used SPRT technique to deal with the INAR model. Godase and Mahadik [24] introduced an SPRT dispersion chart.

Keeping in view of several dynamic aspects of SPRT and sequential sampling, we intend to design a sequential algorithm-based EWMA chart, named SEWMA_β. This scheme uses two pairs of control limits as follows in SPRT. The novelty of this article is to propose a more flexible EWMA control chart for monitoring the process location by employing an SPRT decision algorithm. The rest of this paper is organized as follows: Section 2 provides the design structure of the proposed sequential EWMA chart. Section 3 demonstrates procedural flow for the computation of run length measures. The performance evaluation and comparative analysis are provided in Section 4. A real-life application concerning the monitoring of breaking strength of steel rods is presented in Section 5. Finally, Section 6 lists the main finding and recommendations of the study.

2. Design structure of the proposed SEWMA_β chart

This section provides the design structure of the proposed chart. For the rest of the current article, we will denote the proposed chart as a SEWMA_β chart. In the SPRT technique, observations are taken in groups of one or more observations. If the single observation falls in an indecision zone then another observation is taken until a decision is achieved. For the sake of simplicity, we have used individual observations for this study; however, subgroups of different sizes may also be considered on similar lines (cf. Wald [25]).

Let $X_1, X_2, X_3 \dots \dots \dots, X_n$ be a set of independent individual observations, selected from a specific probability distribution (say normal distribution). An

individual observation may be classified into three non-overlapping regions categorized as

Region I: the acceptance region (where the process is considered to be in-control);

Region II: the resampling region (where the process needs to be resampled);

Region III: the rejection region (where the process is considered to be out-of-control).

For a single observation, let α be the probability of falling in the rejection region and γ be the probability of falling in the indecision region. Then under a resampling setup, the respective probabilities for the three regions are given as shown in Figure 1.

Let us denote R_s as the resampling region. Now based on observed sample values X_{j_s} we may define a plotting statistic, say Z_j , of the SEWMA_β chart as follows:

$$Z_j = \lambda_g I_j + (1 - \lambda_g) Z_{j-1}, \quad j = 0, 1, 2, \dots, \quad (1)$$

where $E[Z_0] = \mu_0$ and $0 < \lambda_g \leq 1$. Also for compactness, we can alternatively denote I_j as follows:

$$I_j = \begin{cases} X_j & \text{if } X_j \notin R_s \\ X_j + \sum_{k=1}^{N_j} Y_{j,k} & \text{if } Z_j \in R_s \end{cases} \quad (2)$$

where N_j is the number of data points sequentially sampled in the j th monitoring batch, k is just the counter for the sequential sampling, and $Y_{j,k}$ is the resampled point in the k th sequence of the j th monitoring batch. Or alternatively, we can denote I_j as

$$I_j = X_j + \sum_{k=0}^{N_j} Y_{j,k}, \text{ when } X_j \notin R_s.$$

We note that the probability of a sample $Z_j \in R_s$ is given by $P(Z_j \in R_s) = \gamma$. Samples will be drawn at each stage j until $Z_j \notin R_s$. Moreover, for simplicity of derivations and for finding the first two centred moments of Z_j , we will use the transformation $\lambda_g^* = 1 - \lambda_g$ (check Appendix for details). It is to be mentioned that λ_g is the smoothing or the weighting factor ($0 < \lambda_g \leq 1$) and it may take varying values depending on how frequently the monitoring statistic is falling in the indecision region. In other words, it may be used to cater to the sensitivity of the shifts that might occur in a process. The initial value of SEWMA_β statistic is usually set to be $Z_0 = \mu_0$. Moreover, X and Y are independently distributed random variables that follow the normal distribution with μ_0 as mean and variance σ_0^2 .

The mean and variance of SEWMA_β statistic are

$$\left. \begin{aligned} \mu_{Z_j} &= \mu_0 \left(1 + \frac{1}{1-\gamma} \right) \\ \sigma_{Z_j}^2 &= \left(1 + \frac{1}{1-\gamma} \right) \left(\frac{1-\lambda_g^*}{1+\lambda_g^*} \right) \sigma_0^2 + \frac{\gamma}{(1-\gamma)^2} \left(\frac{1-\lambda_g^*}{1+\lambda_g^*} \right) \mu_0^2 \end{aligned} \right\} \quad (3)$$

It is to be mentioned that the abovementioned expressions are asymptotic versions of mean and variance of

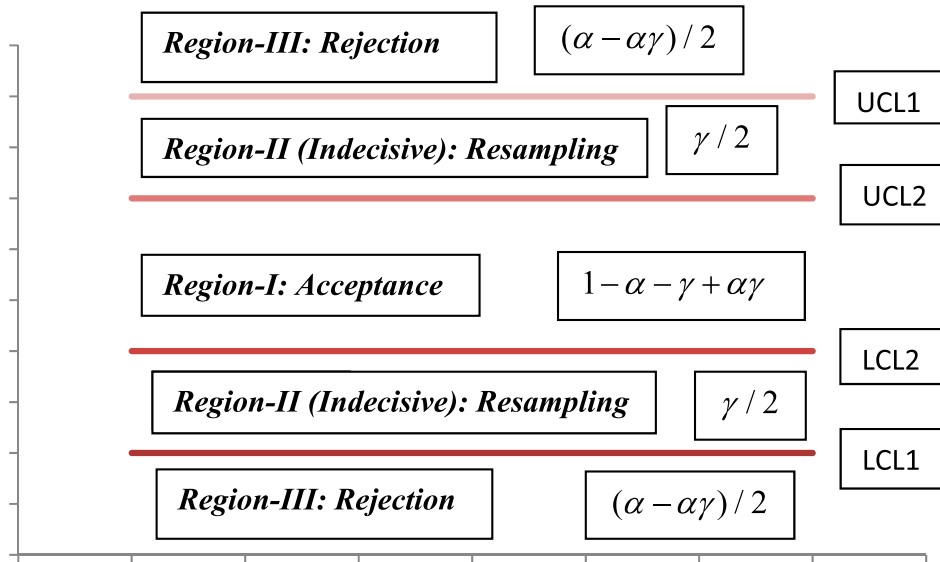


Figure 1. A graphical display of decision regions under sequential algorithm.

Z_j (cf. Appendix). The details regarding the derivations of these expressions can be seen in the Appendix.

The control limits of the proposed $SEWMA_{\beta}$ control chart are in the form of two pairs of upper and lower control limits because of the three regions (as indicated in Figure 1). Using the expressions given in Equation (3) and the splitted regions in Figure 1, the control limits of the proposed $SEWMA_{\beta}$ chart are defined as

$$\left. \begin{aligned} LCL_2 &= \mu_{Z_j} - L_2\sigma_{Z_j} \\ UCL_2 &= \mu_{Z_j} + L_2\sigma_{Z_j} \\ LCL_1 &= \mu_{Z_j} - L_1\sigma_{Z_j} \\ UCL_1 &= \mu_{Z_j} + L_1\sigma_{Z_j} \end{aligned} \right\}, \quad (4)$$

where LCL_1 , UCL_1 determine the out-of-control and LCL_2 , UCL_2 determine the in-control regions, respectively, and accordingly the inner region (i.e. the area between UCL_1 & UCL_2 and LCL_1 & LCL_2) corresponds to the indecision region where we need to resample (cf. Figure 1). It is to be mentioned that when the monitoring statistic falls in the indecision region, we continue resampling and keep updating the plotting statistic (using the new sample information) until it falls in one of the decisive regions (i.e. Regions I or III). The quantities L_1 and L_2 are the control limit coefficients that are used to adjust the in- and out-of-control limits to achieve the desired in-control average run length (denoted by ARL_0). These coefficients must hold the condition that $L_1 \geq L_2$. Note that for $L_1 = L_2$, the performance of $SEWMA_{\beta}$ chart is exactly the same as the usual EWMA chart.

i. Percentile Adjustment for Indecision zone

In the sequential sampling setup, it is important to adjust the indecision zone in order to achieve the desirable properties corresponding to a prespecified ARL_0 . In this study, we adjust the width of the indecision region,

according to the following relation

$$L_2 = L - \beta L, \quad (5)$$

where L is the control limit coefficient (at a prespecified ARL_0) for the $SEWMA_{\beta}$ chart, which matches its performance with the EWMA chart (i.e. $L_1 = L_2 = L$), and β is the factor used to adjust the width of the decisive zone, $0 \leq \beta \leq 1$. For $\beta = 0$, $L_1 = L_2 = L$, the performance of the $SEWMA_{\beta}$ chart is exactly the same as the proposed $SEWMA_{\beta}$ chart.

2.1. Decision criteria

Using Equations (3)–(6), we compute the two pairs of control limits for a fixed ARL_0 . For each new monitoring sample, we calculate the plotting statistic Z_j using Equation (1) sequentially. If the plotting statistic Z_j falls in one of the decisive regions I or III, then we make the decision accordingly. If Z_j falls in the indecision region, we continue resampling to update the plotting statistic (using the new sample information), until it falls in one of the decisive regions (i.e. Regions I or III). Figure 2 provides an exemplary charting display for the proposed $SEWMA_{\beta}$ chart.

It is to be noted that: (i) the sensitivity of the regions may be controlled by the design parameters, namely λ_g , β , L_1 and L_2 ; (ii) for the sake of simplicity, we have used $\lambda_g = \lambda$ for each occasion where we needed to resample; (iii) classical EWMA chart is a special case of the proposed chart when $L_1 = L_2 = L$.

3. Performance evaluation techniques

To assess the performance of the $SEWMA_{\beta}$ chart, we have used different run length properties, such as the average (ARL), the median (MRL) and the standard deviation of the run length (SDRL) distribution. ARL is the

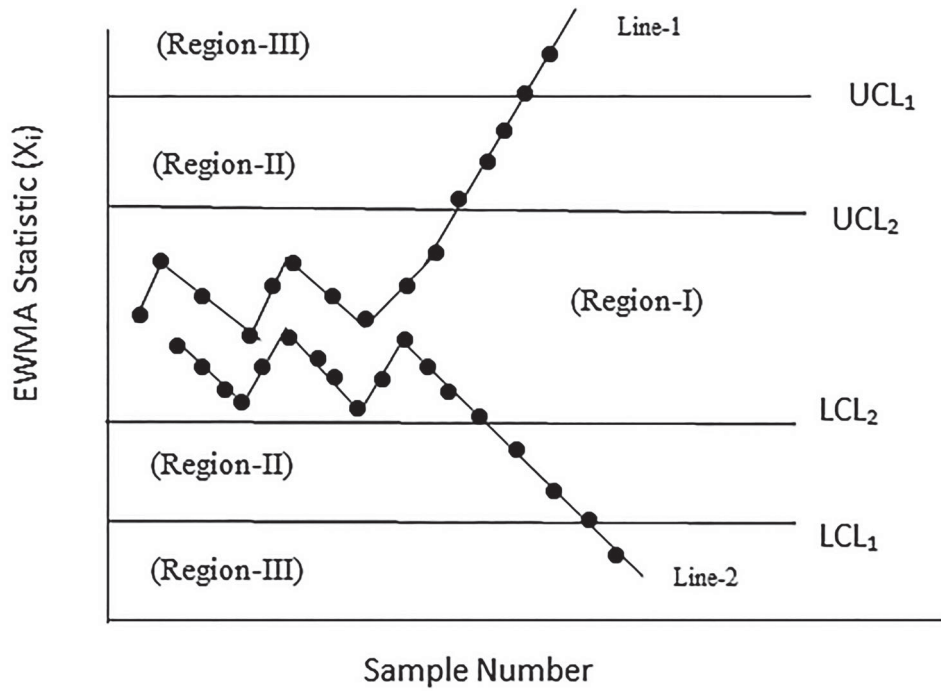


Figure 2. A charting display for the SEWMA_β control chart.

frequently used measure to evaluate the performance of control charts. ARL can be categorized into in-control (IC) average run length (ARL₀) and out-of-control ARL (ARL₁), defined as

ARL₀: Average number of samples plotted on a control chart *until the first point goes outside* the limits, when the process is *in-control* (IC).

ARL₁: Average number of samples plotted on a control chart *until the first point goes out* of the limits, when the process is *out-of-control* (OOC).

Similarly, MRL and SDRL can be defined based on an in-control or out-of-control state of the process.

To examine the detection ability of the SEWMA_β chart, shifts are introduced in the in-control (IC) process location say, μ_0 and the OOC process mean level is defined as $\mu_1 = \mu_0 + \delta\sigma_0$, where δ refers to the amount of shift.

These run length properties may be calculated by using the following expressions (cf. Chakraborti [26], Khaliq et al.[27])

$$ARL = \text{Expected}(RL) = \int_{-\infty}^{+\infty} (RL)f(RL)d(RL). \quad (6)$$

$$SDRL = \sqrt{E(RL^2) - [E(RL)]^2}. \quad (7)$$

$$\begin{aligned} MRL &= p(RL \leq m) = p(RL > m) \\ &= \int_{-\infty}^m f(RL)d(RL) = 0.5. \end{aligned} \quad (8)$$

3.1. Algorithm for SEWMA_β chart construction

In this subsection, we discuss how to construct the SEWMA_β chart via an algorithm. The following are

the necessary steps of the algorithm to achieve this work.

- (i) Draw a random observation from a normal distribution with in-control mean μ_0 and standard deviation σ_0 . Without loss of generality, we used $\mu_0 = 0$ and $\sigma_0 = 1$. Find the monitoring statistic for the SEWMA_β chart (using Equation (1)).
- (ii) Select $L_1 = L_2 = L$ and plot the monitoring statistic (using the criterion mentioned in (2)) against the control limits (given in Equation (4)), to achieve the desired IC-ARL₀.
- (iii) Decide L_2 using Equation (5) after selecting a level of p . For a given specified L_2 , L_1 is then chosen to achieve the desired ARL₀.

We now discuss the simulation procedure to assess the performance of the SEWMA_β chart.

3.2. Algorithm for RL properties

Monte Carlo simulations are used to obtain the RL properties of the SEWMA_β chart, following Quesenberry [28] and Khaliq et al.[29]. The steps taken in the simulation study are as follows.

- (i) With the sequential charting algorithm described in the previous subsection, construct the SEWMA_β chart.
- (ii) For getting out-of-control RL, shifts are introduced in the process mean level by plotting the monitoring statistic of the shifted samples against the control limits (using the criterion mentioned in Equation (2)). The OOC run length is computed as

the number of samples plotted on the control chart before the first point goes beyond LCL2 or UCL2.

- (iii) The process is repeated 100,000 times to record RL values of the proposed design.
- (iv) Using the RL's from step (iii) above, the ARL, MRL and SDRL are computed as the mean, median and standard deviations of these RLs respectively.

4. Performance evaluation and comparisons

In this section, we evaluate the performance of the proposed SEWMA $_{\beta}$ chart at different levels of design parameters λ , β , and ARL_0 , L_1 and L_2 . The performance of the proposed SEWMA $_{\beta}$ chart is compared with some existing charts for efficient detection of shifts in the process mean level. Tables 1–3 provide the RL properties of the proposed SEWMA $_{\beta}$ chart and the competing charts such as EWMA, CUSUM and FIR-EWMA charts for varying values of λ , β and δ . Moreover, Figures 1 and 2 provide a graphical comparison of the performance of the proposed SEWMA $_{\beta}$ chart at varying levels of design parameters.

4.1. SEWMA $_{\beta}$ performance analysis

This section is about the *Run Length (RL)* performance of SEWMA $_{\beta}$ chart by varying β and λ . Several performance measures were used to observe the performance of the proposed design, i.e. average, median and standard deviation (cf. ARL, MRL and SDRL). Tables 1 and 2 represent the ARL $_1$, MRL and SDRL performance of SEWMA $_{\beta}$ versus EWMA chart by varying λ and β . Here, λ is the smoothing or weighting factor that has a similar effect on the performance of the EWMA chart. The β has a significant impact on the performance of the SEWMA $_{\beta}$ chart. Here, β is control limits adjusting factor (percentile) and it guarantees the better ARL $_1$ performance of SEWMA $_{\beta}$ chart. Several choices of β are 2%, 4%, 6%, 8%, 10% and 12%. It may be observed from the tables that we have smaller ARL $_1$, MRL and SDRL values from SEWMA $_{\beta}$ than classical EWMA.

i. ARL $_1$ Performance Analysis

Although both designs performed equally well based on the ARL under the in-control situation, our proposed design has better ARL $_1$ performance in the out-of control situations than the classical EWMA chart as it has smaller ARL $_1$ for all choices of β . As an illustration, consider Table 2; EWMA chart shows ARL $_1 = 282$ while SEWMA $_{\beta}$ at $\beta = 2\%$, 4%, 6%, 8%, 10% and 12% are 272.51, 264.29, 256.36, 173.4, 232.68 and 271, respectively, for $\lambda = .9$ and $\delta = .2$. That is, SEWMA $_{\beta}$ charts have better ARL $_1$ than classical EWMA chart. This performance gain may be observed up to a process shift of $\delta = 4$. Similar ARL behaviour may be observed from Tables 1 and 2. Figures 3 and 4 also support these results.

ii. MRL Performance Analysis

SEWMA $_{\beta}$ not only have better ARL $_1$ but it also performed well considering median RL properties. EWMA and SEWMA $_{\beta}$ are equally efficient at $\beta = 5\%$. However, our design has smaller MRL values for small to moderate shift at $\beta = 4\%$, 6%, 8%, 10%, and 12%. Consider Table 2. The MRL values of EWMA is 282.14 while for SEWMA $_{\beta}$, MRL values are 272.51 (2%), 264.29 (4%), 256.36 (6%), 173.4 (8%), 232.68 (10%) and 217.25 (12.5%). Furthermore, it may be observed from Tables 1 and 2, our proposed design showed better MRL values up to shift of $\delta = 1.75$ at $\lambda = 0.99, 0.5, 0.25$ and 0.05.

iii. SDRL Performance Analysis

SEWMA $_{\beta}$ has smaller SDRL values than EWMA up to $\delta = 3$. SEWMA $_{\beta}$ outperformed the EWMA chart at $\lambda = 0.99, 0.5, 0.25$ and 0.05 up to $\delta = 3$. As an example, consider Table 2. For $\delta = .25$, our proposed design showed SDRL values of 273.04 (2%), 261.04 (4%), 252.04 (6%), 171.883 (8%), 227.37 (10%) and 214.32 (12.5%) while EWMA showed SDRL of 282.14. Similar SDRL behaviour may be observed from Tables 1 and 2. That is, our proposed design has a smaller variation in RL than the classical EWMA design.

4.1.1. General Comments

The proposed SEWMA $_{\beta}$ chart has better ARL, MRL and SDRL performance than the classical EWMA design. The proposed design is more efficient than the classical one from small, moderate and larger shifts. In particular, SEWMA $_{\beta}$ is more efficient than the EWMA chart when $\beta > 0.02$ as may be seen in Figures 3 and 4. It is to be noted that the SEWMA $_{\beta}$ reduces to the EWMA chart when $\beta = 0$.

4.2. Comparative analysis of SEWMA $_{\beta}$ versus EWMA, CUSUM and FIR-EWMA

This section is designed to show the comparative performance of SEWMA $_{\beta}$ versus classical EWMA, CUSUM and FIR-EWMA chart using several ARL $_0$ values. Table 3 demonstrates the ARL performance of SEWMA $_{\beta}$ ($\beta = 10\%$ and 12.5%) against classical EWMA and CUSUM design at ARL $_0 = 168, 400$ and 500. Moreover, Table 3 also presents the ARL performance of SEWMA $_{\beta}$ ($\beta = 10\%$ and 12.5%) versus FIR-EWMA at ARL $_0$. The findings are as discussed below.

i. SEWMA $_{\beta}$ versus EWMA and CUSUM charts at ARL $_0 = 168, 400$ and 500.

Table 3 shows the ARL performance of SEWMA $_{\beta}$ versus EWMA and CUSUM charts using ARL $_0 = 168, 400$ and 500. It may be perceived that SEWMA $_{\beta}$ has smaller ARL $_1$ values than EWMA until a shift parameter of $\delta = 2$ while it has better performance than CUSUM up to $\delta = 1.5$. SEWMA $_{\beta}$ chart ($\beta = 10\%$ and 12.5%) has

Table 2. RL properties of SEWMA $_{\beta}$ and EWMA ($L_1 = L_2$) charts for varying δ and β when $\lambda = 0.50$ and 0.99 at $ARL_0 = 370$.

		$\lambda = 0.50$								$\lambda = 0.99$							
β		0	0.02	0.04	0.06	0.08	0.1	0.125	0	0.02	0.04	0.06	0.08	0.1	0.125		
L_1		1.7176	1.7580	1.8146	1.9001	2.0317	2.2014	2.4699	4.1691	4.2553	4.3970	4.6444	4.7667	5.4866	6.2954		
L_2		1.7176	1.6836	1.6489	1.6148	1.5802	1.5461	1.5028	4.1691	4.0857	4.0024	3.9190	3.8356	3.7522	3.6480		
0	ARL	370.65	369.53	369.36	369.16	369.29	368.68	370.45	370.61	369.68	368.47	371.67	369.97	370.94	371.45		
	MDRL	262.00	258.00	255.00	255.00	254.00	253.00	257.50	259.00	255.00	256.00	257.00	254.00	256.00	259.00		
	SDRL	370.48	368.88	366.84	365.94	367.20	373.17	371.90	371.57	373.98	367.22	371.72	370.87	371.43	373.03		
0.25	ARL	195.37	190.57	182.94	176.81	169.27	160.20	148.79	282.14	272.51	264.29	256.36	173.40	232.68	217.25		
	MDRL	136.00	131.00	126.00	122.00	117.00	112.00	102.00	194.00	187.00	182.00	178.00	119.00	165.00	152.00		
	SDRL	193.04	190.75	183.04	175.05	166.64	156.53	147.47	283.21	273.04	261.83	252.56	171.83	227.37	214.32		
0.5	ARL	70.89	67.59	63.89	60.33	56.75	52.38	46.50	155.53	144.39	135.22	125.01	58.32	103.21	88.90		
	MDRL	49.00	47.00	45.00	42.00	39.00	37.00	33.00	108.00	100.00	95.00	87.00	41.00	71.00	61.00		
	SDRL	69.40	65.56	61.68	58.37	55.13	50.14	44.84	153.73	142.99	132.96	125.10	56.48	102.76	89.22		
0.75	ARL	30.29	28.75	26.86	25.05	23.32	21.60	19.43	80.65	73.82	67.25	61.11	24.11	48.56	41.35		
	MDRL	22.00	21.00	19.00	18.00	17.00	16.00	14.00	57.00	52.00	47.00	42.00	17.00	34.00	29.00		
	SDRL	28.35	26.37	24.68	22.87	20.96	19.49	17.39	78.88	72.76	65.99	60.02	21.78	47.51	40.40		
1	ARL	15.27	14.42	13.63	12.80	11.98	11.21	10.19	44.02	39.56	35.45	32.15	12.28	25.35	21.81		
	MDRL	11.00	11.00	10.00	10.00	9.00	8.00	8.00	31.00	28.00	25.00	23.00	9.00	18.00	15.00		
	SDRL	13.02	12.37	11.55	10.83	10.09	9.41	8.53	43.31	38.50	34.29	31.00	10.34	24.70	21.08		
1.25	ARL	8.89	8.48	8.04	7.57	7.17	6.78	6.32	25.18	22.47	20.31	18.23	7.31	14.62	12.68		
	MDRL	7.00	6.00	6.00	6.00	6.00	5.00	5.00	18.00	16.00	14.00	13.00	6.00	10.00	9.00		
	SDRL	7.01	6.63	6.27	5.82	5.45	5.15	4.73	24.64	22.03	19.69	17.55	5.63	14.04	12.05		
1.5	ARL	6.00	5.73	5.44	5.23	4.97	4.76	4.46	15.17	13.68	12.33	11.13	5.06	9.06	7.96		
	MDRL	5.00	5.00	4.00	4.00	4.00	4.00	4.00	11.00	10.00	9.00	8.00	4.00	6.00	6.00		
	SDRL	4.19	3.95	3.70	3.53	3.35	3.15	2.89	14.49	13.06	11.75	10.54	3.41	8.49	7.39		
1.75	ARL	4.39	4.21	4.03	3.88	3.70	3.55	3.40	9.52	8.65	7.86	7.17	3.76	5.94	5.30		
	MDRL	4.00	4.00	3.00	3.00	3.00	3.00	3.00	7.00	6.00	6.00	5.00	3.00	4.00	4.00		
	SDRL	2.72	2.58	2.42	2.31	2.18	2.07	1.95	8.95	8.11	7.23	6.62	2.24	5.46	4.80		
2	ARL	3.42	3.29	3.18	3.08	2.97	2.86	2.75	6.30	5.75	5.25	4.87	3.02	4.14	3.77		
	MDRL	3.00	3.00	3.00	3.00	3.00	3.00	2.00	5.00	4.00	4.00	4.00	3.00	3.00	3.00		
	SDRL	1.84	1.76	1.69	1.61	1.54	1.48	1.40	5.75	5.21	4.70	4.31	1.58	3.62	3.23		
2.5	ARL	2.39	2.33	2.26	2.20	2.13	2.08	2.00	3.23	3.03	2.83	2.67	2.16	2.39	2.23		
	MDRL	2.00	2.00	2.00	2.00	2.00	2.00	2.00	2.00	2.00	2.00	2.00	2.00	2.00	2.00		
	SDRL	1.07	1.05	1.02	1.00	0.97	0.94	0.91	2.65	2.45	2.27	2.11	0.97	1.81	1.64		
3	ARL	1.85	1.80	1.76	1.71	1.68	1.65	1.60	2.02	1.91	1.83	1.76	1.69	1.63	1.56		
	MDRL	2.00	2.00	2.00	2.00	2.00	2.00	2.00	2.00	1.00	1.00	1.00	2.00	1.00	1.00		
	SDRL	0.75	0.73	0.72	0.71	0.69	0.68	0.66	1.41	1.31	1.22	1.15	0.69	1.01	0.92		
3.5	ARL	1.52	1.49	1.46	1.43	1.40	1.37	1.34	1.45	1.41	1.37	1.33	1.41	1.27	1.23		
	MDRL	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00		
	SDRL	0.58	0.58	0.56	0.55	0.54	0.53	0.52	0.80	0.75	0.71	0.66	0.55	0.59	0.54		
4	ARL	1.30	1.27	1.25	1.23	1.20	1.18	1.16	1.19	1.17	1.15	1.13	1.21	1.10	1.09		
	MDRL	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00		
	SDRL	0.47	0.46	0.44	0.43	0.41	0.39	0.37	0.47	0.44	0.41	0.39	0.42	0.34	0.31		

Table 3. ARL performance of EWMA, FIR-EWMA, CUSUM and SEWMA $_{\beta}$ charts when $\lambda = .25$ and $ARL_0 = 168,400, 500$.

Control chart	δ								
	0	0.25	0.5	0.75	1	1.25	1.5	1.75	2
EWMA	167.76	74.89	27.44	13.52	8.21	5.78	4.44	3.62	3.07
CUSUM	167.2	74.31	26.65	13.4	8.37	6.05	4.77	3.35	2.45
SEWMA($\beta = 0.1$)	168.66	68.01	23.59	11.5	7.05	5.05	3.91	3.21	2.76
SEWMA($\beta = 0.125$)	167.9	65.09	23.33	10.91	6.74	4.84	3.78	3.12	2.68
EWMA	400.98	146.32	43.01	18.7	10.5	7.04	5.27	4.19	3.5
CUSUM	402.17	129.87	35.78	16.37	10.06	7.15	5.62	3.9	2.33
SEWMA($\beta = 0.1$)	399.69	123.96	34.77	15.32	8.73	6	4.56	3.86	3.1
SEWMA($\beta = 0.125$)	399.33	116.45	32.28	14.32	8.26	5.71	4.37	3.54	3
EWMA	502.52	171.46	48.66	20.4	11.19	7.39	5.47	4.34	3.62
CUSUM	500	143.87	37.71	17.29	10.53	7.49	5.77	4.04	3.67
SEWMA($\beta = 0.1$)	501.54	147	38.46	16.4	9.19	6.26	4.72	3.77	3.19
SEWMA($\beta = 0.125$)	500.65	135.71	35.34	15.34	8.66	5.95	4.51	3.66	3.08
EWMA	502.52	171.46	48.66	20.4	11.19	7.39	5.47	4.34	3.62
FIR-EWMA	515	169.8	47.6	19.5	10.6	5	3.1	1.7	1.2
SEWMA($\beta = 0.1$)	501.54	147	38.46	16.4	9.19	6.26	4.72	3.77	3.19
SEWMA($\beta = 0.125$)	500.65	135.71	35.34	15.34	8.66	5.95	4.51	3.66	3.08

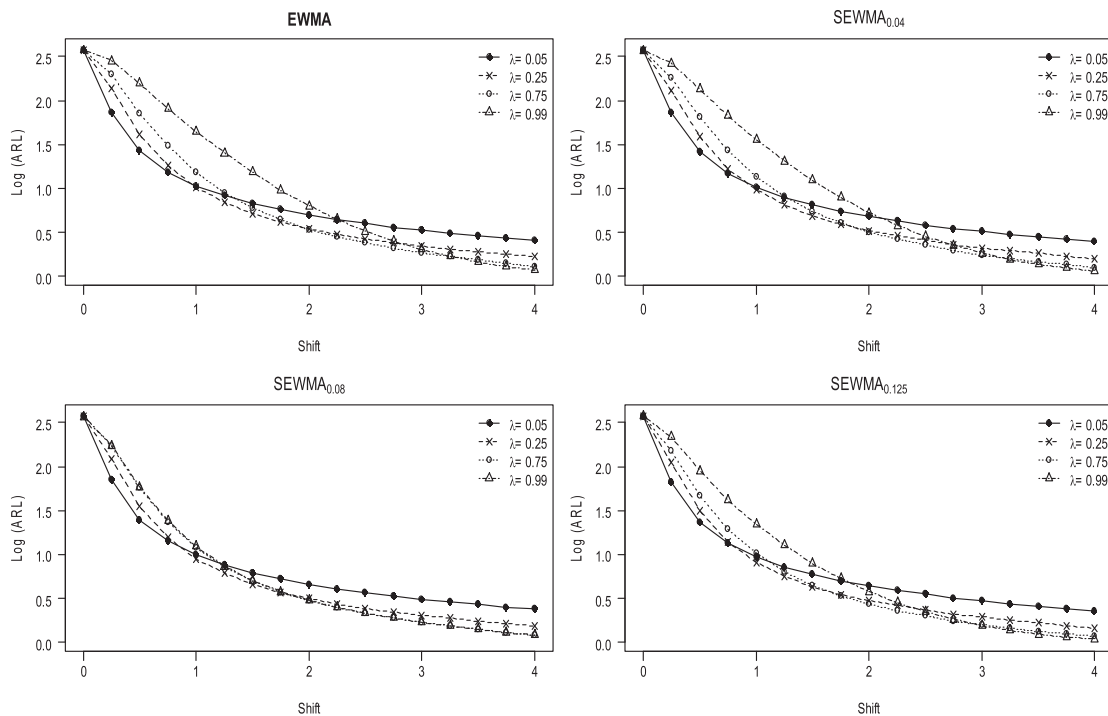


Figure 3. ARL comparison of EWMA and SEWMA $_{\beta}$ charts when $ARL_0 = 370$ and $\lambda = 0.05, 0.25, 0.50$ and 0.99 .

ARL values of 147 and 135.71, respectively, whereas the same values for CUSUM and EWMA are, respectively, 143.87 and 171.46 at $ARL_0 = 500$ and $\delta = .25$. Similar ARL performance may be observed for $ARL_0 = 168$ and 400.

ii. SEWMA $_{\beta}$ versus FIR-EWMA charts at $ARL_0 = 500$

Table 3 exhibits the comparative ARL performance of SEWMA $_{\beta}$ using ($\beta = 10\%$ and 12.5%) versus FIR-EWMA at $ARL_0 = 500$ (cf. [30]). From Table 3, the ARL_1 values for SEWMA $_{\beta}$ $\beta = 10\%$ and 12.5% at $\delta = .25$ are 147.71 and 135.1, respectively. FIR-EWMA exhibits ARL of 47.6 which is smaller than EWMA. Although similar ARL_1 may be observed for other shifts, SEWMA $_{\beta}$ showed better ARL_1 than FIR-EWMA for shifts up to $\delta = 1.5$.

4.2.1. General Comments

The proposed design exhibits better performance than EWMA for all choices of $\beta > 0$. As β increases, the performance of the SEWMA $_{\beta}$ chart becomes increasingly better than EWMA, especially for higher values of smoothing parameter λ (cf. Table 3). The proposed SEWMA $_{\beta}$ chart outperforms the CUSUM chart at all levels of shift δ . The performance of the SEWMA $_{\beta}$ chart (compared with CUSUM chart) gets better with increase in p . Table 3 also provides the comparison of SEWMA $_{\beta}$ chart ($\beta = 10\%$ and 12.5%) versus FIR-EWMA at $\lambda = .25$ and $ARL_0 = 500$ [36]. It is noticed that as β increases, SEWMA $_{\beta}$ chart is more sensitive for the detection of shifts as compared with FIR-EWMA chart (cf. last row of Table 3). Overall, the proposed SEWMA $_{\beta}$ chart performs

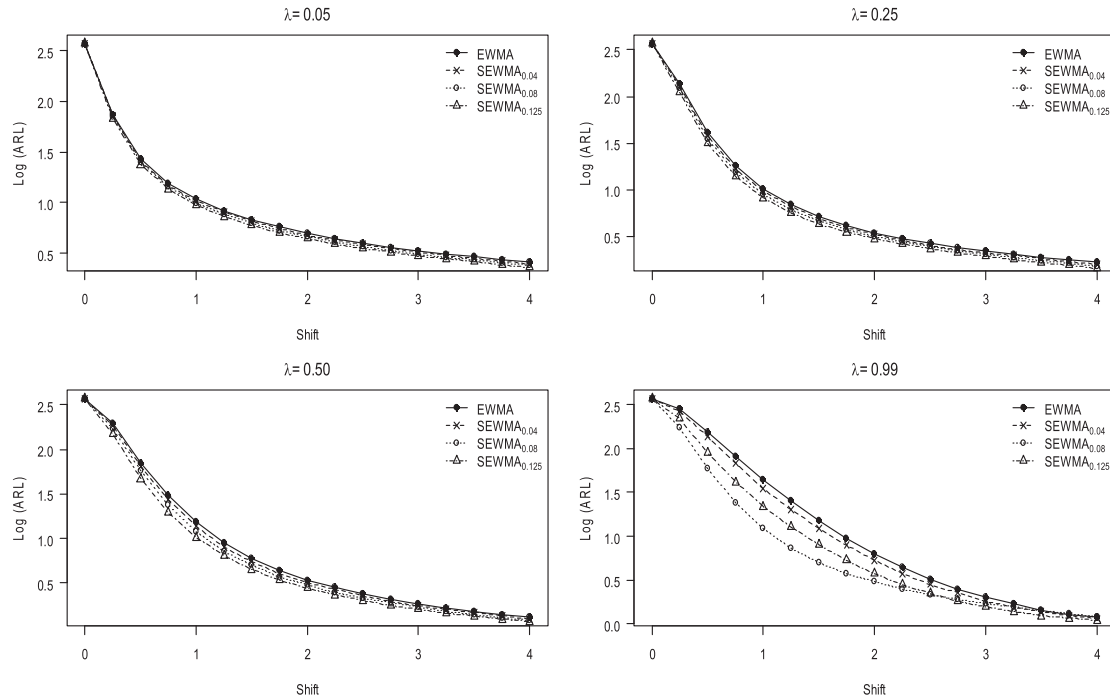


Figure 4. ARL comparison of EWMA and $SEWMA_{\beta}$ charts (at different levels of β) when $ARL_0 = 370$ and $\lambda = 0.05, 0.25, 0.50$ and 0.99 .

better than other competing charts (such as EWMA, CUSUM and FIR-EWMA charts) for detecting shifts in the process mean level. The performance of the $SEWMA_{\beta}$ chart relies mainly on the choice of λ and β . The detection ability of the $SEWMA_{\beta}$ chart improves with an increase in p at all levels of λ . For a fixed β , if the interest is in the detection of small shifts, it is recommended to use low values of λ (i.e. $\lambda = 0.05$ or 0.25). In the next section, a real-life application for monitoring the strength of steel rods is presented.

It is to be mentioned that the current study is designed under normality; however, one may extend this for other distributional environments such as Maxwell, Weibull, Burr, Power, etc. (cf. Al Mutairi and Volodin [31], Basheer [32], Haq et al. [33], Hossain et al. [34, 35]).

5. A real application of $SEWMA_{\beta}$ to steel rod manufacturing industry

This section presents a real-life application of the proposed technique in a production line that relates to an ongoing monitoring process of steel rod manufacturing. The steel industry is a booming industry and it plays an essential role in the development of a country and helps strengthen the economy. Most of the steel manufactured by an aluminium plant or a steel mill is moulded through extrusion or rolling into long continuous strips of numerous shape and size. Several testing techniques are commercially available and can be customized to meet specific inspection needs. Whether manual, automated or phased array, ultrasonic

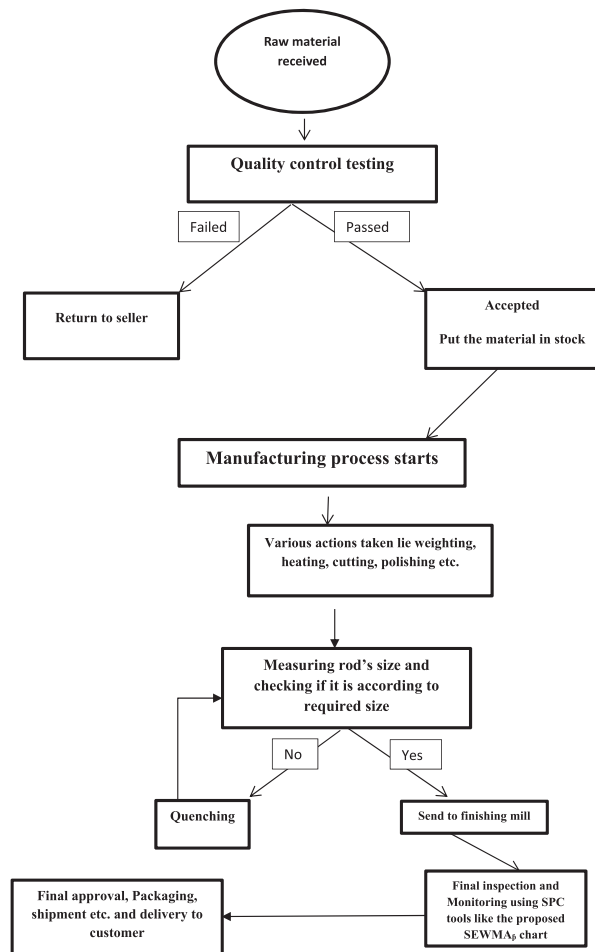


Figure 5. A flow of $SEWMA_{\beta}$ design in steel rod manufacturing process

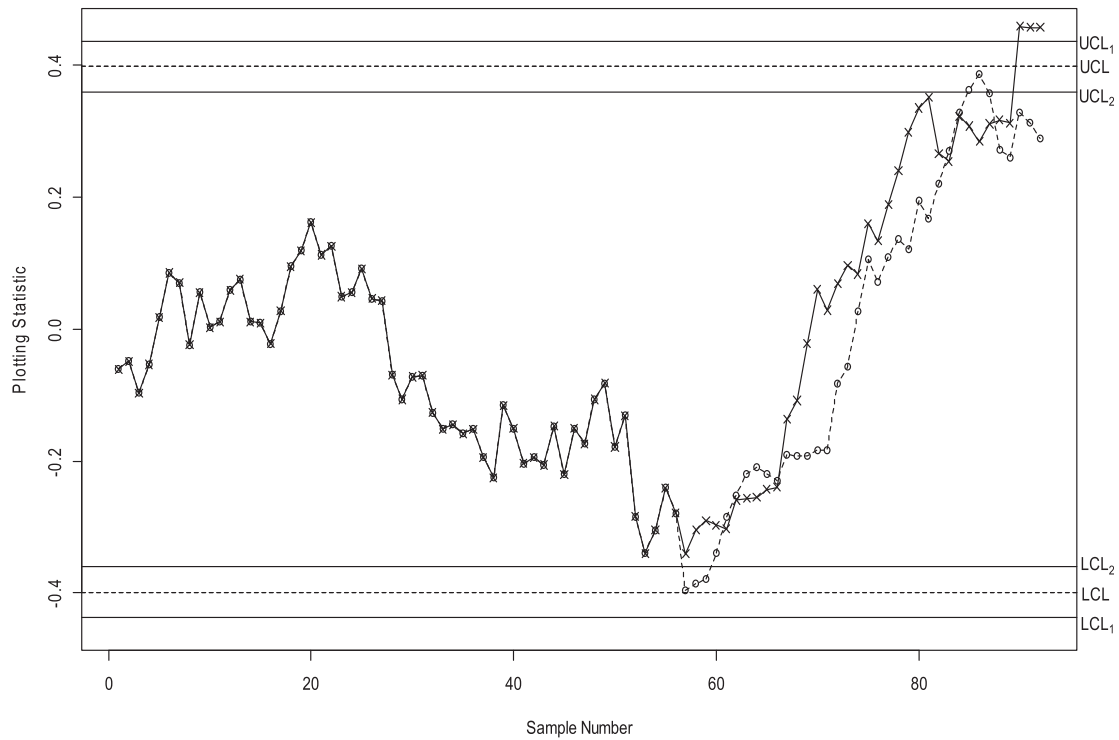


Figure 6. Control charts of the EWMA and $SEWMA_{\beta}$ for the steel rod data when $\lambda = 0.05$ and $\beta = 0.1$.

testing can help manufacturers of bars, tubing and related metal products to assure product quality and customer satisfaction. But without proper SPC techniques, it will be time consuming and costly. To reduce the cost, it is necessary to use such techniques which provide a timely identification of any deviations from the stable state of a process. Several authors designed efficient SPC techniques to identify the unusual variations present during several processes. Lyu and Chen [36] designed a multivariate SPC technique to detect defects which often occur during manufacturing process. Pérez-González et al. [37] applied SPC to get the proper decision from the entire emergency and security system. In several steel manufacturing industries, quality control techniques are implemented to enhance process monitoring of designing and manufacturing steel rods. Christyanti [38], Naeem et al. [39] and the references therein may be seen for further details related to the topic. They used different statistical approaches like DOE (design of experiment) and \bar{X} chart for the identification of special causes. They suggested that 6-sigma procedures really helps to identify the special causes during process monitoring. Figure 5 provides a graphical representation of the monitoring process in steel rod manufacturing, where one can potentially use the proposed $SEWMA_{\beta}$ chart.

The data we have used here is related to the steel manufacturing industry. The breaking strength of the rods is our quality characteristic of interest that needs monitoring over time for a better quality of the products related to the process output. A sample of 90 steel rods measurements is collected from the aforementioned process, and their breaking strength is

measured. Through distribution fitting tests, we identified that the breaking strengths of the steel rods follow a normal distribution. We have constructed $SEWMA_{\beta}$ and the classical EWMA charts for this dataset using $\lambda = .05$ and $\beta = 0.1$. Figure 6 presents these comparative charts where UCL and LCL refer to limits of the classical EWMA, while the other two pairs (LCL_1 , UCL_1) and (LCL_2 , UCL_2) correspond to the $SEWMA_{\beta}$ chart. It is observed that the proposed design is not only indicating the shift earlier than the classical EWMA, but it is also giving a larger number of out-of-control signals (this is exactly in accordance with the findings in Section 4).

These earlier and larger detections by $SEWMA_{\beta}$ design has many practical implications for process monitoring. It may be used as a tool needed to reduce the amount of labour and to perform cost-effective experimentations. The potential factors causing out-of-control signals might include changes in these factors: mechanical properties of metal, hardness level, yield strength, intensity of temperature, the grain size, atmospheric pressure, the quality of the protective surface film, the presence of certain agents reducing any corrosive effects, the presence of surface cracks or discontinuities and other environmental condition. These kinds of abnormalities may be identified by using appropriate SPC techniques such as the newly proposed $SEWMA_{\beta}$ chart of this study.

6. Concluding remarks

This study introduces a memory control chart, namely $SEWMA_{\beta}$ chart, for an efficient monitoring of shifts in the process location parameter. The performance of the

proposed design is assessed by using several *RL* properties (such as *ARL*, *MRL* and *SDRL*) at varying values of design parameters λ_g , β , L_1 and L_2 . The results advocate that the proposed design provides enhanced *RL* properties as compared with the classical EWMA, CUSUM and FIR-EWMA charts at several p values. As p increases, the proposed design offers more sensitivity towards shifts in the process mean relative to the competing charts. A real-life application concerning the breaking strength of steel rods highlights the significance of our study.

The current work can be extended to study the performance of CUSUM, mixed / combined Shewhart, EWMA-CUSUM charts both in univariate and multivariate directions for location and dispersion parameters. The scope may further be extended to cover mixed and sequential sampling techniques in SPC for efficient process monitoring of non-normally distributed process.

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Disclosure statement

No potential conflict of interest was reported by the authors.

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Appendix

For derivations of some results in this appendix, we will rely on the following Theorem, which we present without proof, on the moments of the random sum of random variables from Klugman et al. (2014)

Theorem 1: ([40], Equation (9.9)). Let the random sum, $S = \sum_{j=1}^N X_j$ where X_j is iid from any distribution $f(x; \mu, \sigma^2)$ and the size random variable, N , has a distribution $h(n; m, \pi)$. Then, the first two moments of S are as follows:

$$E(S) = E(N)E(X) \quad \text{and} \quad \text{Var}(S) = E(N)\text{Var}(X) + \text{Var}(N)(E(X))^2.$$

Definition 1: Let us denote R_s as the resampling region. With $0 < \lambda_g \leq 1$ and for $j = 1, 2, 3, \dots$, the sequential EWMA random variable Z_j is defined as follows $Z_j = \lambda_g I_j + (1 - \lambda_g)Z_{j-1}$

$$I_j = \begin{cases} X_j & \text{if } X_j \notin R_s \\ X_j + Y_{j1} & \text{if } Z_{j1} \in R_s \\ X_j + Y_{j1} + Y_{j2} & \text{if } Z_{j2} \in R_s \\ \vdots & \vdots \end{cases} \quad \text{where } E[Z_0] = \mu_0.$$

For compactness, we can alternatively denote I_j as follows:

$$I_j = \begin{cases} X_j & \text{if } X_j \notin R_s \\ X_j + \sum_{k=1}^{N_j} Y_{j,k} & \text{if } Z_j \in R_s. \end{cases}$$

Or alternatively, we can denote I_j as

$$I_j = X_j + \sum_{k=0}^{N_j} Y_{j,k} \quad \text{where } Y_{j0} = \cdot \text{ when } X_j \notin R_s.$$

We note that the probability of a sample $Z_j \in R_s$ is given by $P(Z_j \in R_s) = \gamma$. We note that the random sample $Y_{j,k}$ will be drawn sequentially at each stage j until $Z_j \notin R_s$. As such, the random variable N_j measures the sample size needed until Z_j is outside of the resampling region. Thus, N_j is a geometrically distributed random variable. We also note that the random sample X_j comes from a normal distribution with a mean of μ_0 and variance of σ_0^2 . The sequential random sample $Y_{j,k}$ also comes from a normal distribution with a mean of μ_0 and variance of σ_0^2 . For simplicity of derivations and results for the first

two centred moments of Z_j , we will use the transformation $\lambda_g^* = 1 - \lambda_g$.

A) Derivation of the Mean of Z_j .

1) Mean of Z_1 .

$$\begin{aligned} E[Z_1] &= E[\lambda_g I_1 + (1 - \lambda_g)Z_0] = E[\lambda_g^* Z_0 + (1 - \lambda_g^*)I_1] \\ &= E[\lambda_g^* Z_0 + (1 - \lambda_g^*)I_1] = \lambda_g^* E[Z_0] + (1 - \lambda_g^*) E[E[I_1 | R_s]] \\ &= \lambda_g^* \mu_0 + (1 - \lambda_g^*) E \left[E \left[X_1 + \sum_{k=0}^{N_1} Y_{1,k} | R_s \right] \right] \\ &= \lambda_g^* \mu_0 + (1 - \lambda_g^*) E[E[X_1 | R_s]] + (1 - \lambda_g^*) \\ &\quad \times E \left[E \left[\sum_{k=0}^{N_1} Y_{1,k} | R_s \right] \right] \\ &= \lambda_g^* \mu_0 + (1 - \lambda_g^*) \mu_0 + (1 - \lambda_g^*) E \left[\sum_{k=0}^{N_1} E[Y_{1,k} | R_s] \right] \\ &= \mu_0 + (1 - \lambda_g^*) E[N_1] E[Y_{1,k}] \end{aligned}$$

due to Theorem 1 (by Klugman et al.)⁴¹ where $N_1 \sim \text{geom}(1 - \gamma)$ and $Y_{1,k}$ is iid with μ_0 . Thus

$$\begin{aligned} E[Z_1] &= \mu_0 + (1 - \lambda_g^*) \left(\frac{1}{1 - \gamma} \right) \mu_0 \\ &= \mu_0 \left(1 + \frac{1 - \lambda_g^*}{1 - \gamma} \right). \end{aligned}$$

2) Mean of Z_2 .

$$\begin{aligned} E[Z_2] &= E[\lambda_g^* Z_1 + (1 - \lambda_g^*)I_2] = \lambda_g^* E[Z_1] + (1 - \lambda_g^*) E[E[I_2 | R_s]] \\ &= \lambda_g^* \mu_0 \left(1 + \frac{1 - \lambda_g^*}{1 - \gamma} \right) + (1 - \lambda_g^*) \\ &\quad \times E \left[E \left[X_2 + \sum_{k=0}^{N_2} Y_{2,k} | R_s \right] \right] \\ &= \lambda_g^* \mu_0 + (1 - \lambda_g^*) \mu_0 + \mu_0 \lambda_g^* \left(\frac{1 - \lambda_g^*}{1 - \gamma} \right) \\ &\quad + (1 - \lambda_g^*) E \left[\sum_{k=0}^{N_2} E[Y_{2,k} | R_s] \right] \\ &= \mu_0 + \mu_0 \lambda_g^* \left(\frac{1 - \lambda_g^*}{1 - \gamma} \right) + (1 - \lambda_g^*) E[N_2] E[Y_{2,k}] \end{aligned}$$

due to Theorem 1 (by Klugman et al.)⁴¹ where $N_2 \sim \text{geom}(1 - \gamma)$ and $Y_{2,k}$ is iid with μ_0 . Thus

$$\begin{aligned} E[Z_2] &= \mu_0 + \mu_0 \lambda_g^* \left(\frac{1 - \lambda_g^*}{1 - \gamma} \right) + (1 - \lambda_g^*) \left(\frac{1}{1 - \gamma} \right) \\ \mu_0 &= \mu_0 \left(1 + \frac{1 - \lambda_g^*}{1 - \gamma} (\lambda_g^* + 1) \right) \\ &= \mu_0 \left(1 + \frac{(1 - \lambda_g^*)(1 + \lambda_g^*)}{1 - \gamma} \right). \end{aligned}$$

3) Mean of Z_3 .

$$E[Z_3] = E[\lambda_g^* Z_2 + (1 - \lambda_g^*)I_3] = \lambda_g^* E[Z_2] + (1 - \lambda_g^*) E[E[I_3 | R_s]].$$

By applying Theorem 1 (Klugman et al.)⁴¹ with simplification steps similar to the derivation of $E[Z_2]$, we have,

$$\begin{aligned} E[Z_3] &= \mu_0 + \mu_0 \lambda_g^* \frac{(1 - \lambda_g^*)(1 + \lambda_g^*)}{1 - \gamma} + (1 - \lambda_g^*) \left(\frac{1}{1 - \gamma} \right) \mu_0 \\ &= \mu_0 \left(1 + \frac{(1 - \lambda_g^*)(1 + \lambda_g^* + \lambda_g^{*2})}{1 - \gamma} \right). \end{aligned}$$

4) Mean of Z_4 .

$$E[Z_4] = E[\lambda_g^* Z_3 + (1 - \lambda_g^*) I_4] = \lambda_g^* E[Z_3] + (1 - \lambda_g^*) E[E[I_4 | R_s]]$$

By applying Theorem 1 (Klugman et al.)⁴¹ with simplification steps similar to the derivation of $E[Z_3]$, we have,

$$\begin{aligned} E[Z_4] &= \mu_0 + \mu_0 \frac{(1 - \lambda_g^*)}{1 - \gamma} \lambda_g^* (1 + \lambda_g^* + \lambda_g^{*2}) \\ &\quad + (1 - \lambda_g^*) \left(\frac{1}{1 - \gamma} \right) \mu_0 \\ &= \mu_0 \left(1 + \frac{(1 - \lambda_g^*)}{1 - \gamma} (1 + \lambda_g^* + \lambda_g^{*2} + \lambda_g^{*3}) \right). \end{aligned}$$

5) Mean of Z_j .

The following summarizes the results, we have thus far:

$$\begin{aligned} E[Z_1] &= \mu_0 \left(1 + \frac{1 - \lambda_g^*}{1 - \gamma} \right), \\ E[Z_2] &= \mu_0 \left(1 + \frac{(1 - \lambda_g^*)(1 + \lambda_g^*)}{1 - \gamma} \right), \\ E[Z_3] &= \mu_0 \left(1 + \frac{(1 - \lambda_g^*)(1 + \lambda_g^* + \lambda_g^{*2})}{1 - \gamma} \right), \text{ and} \\ E[Z_4] &= \mu_0 \left(1 + \frac{(1 - \lambda_g^*)(1 + \lambda_g^* + \lambda_g^{*2} + \lambda_g^{*3})}{1 - \gamma} \right). \end{aligned}$$

Based on these, we now let

$$E[Z_{j-1}] = \mu_0 \left(1 + \frac{(1 - \lambda_g^*)}{1 - \gamma} \sum_{k=0}^{j-2} \lambda_g^{*k} \right).$$

Then by induction, we have

$$\begin{aligned} E[Z_j] &= E[\lambda_g^* Z_{j-1} + (1 - \lambda_g^*) I_j] \\ &= \lambda_g^* E[Z_{j-1}] + (1 - \lambda_g^*) E[E[I_j | R_s]] \\ &= \lambda_g^* \mu_0 \left(1 + \frac{(1 - \lambda_g^*)}{1 - \gamma} \sum_{k=0}^{j-2} \lambda_g^{*k} \right) \\ &\quad + (1 - \lambda_g^*) E \left[E \left[X_j + \sum_{k=0}^{N_j} Y_{j,k} | R_s \right] \right] \\ &= \lambda_g^* \mu_0 + (1 - \lambda_g^*) E[E[X_j | R_s]] + \mu_0 \frac{(1 - \lambda_g^*)}{1 - \gamma} \lambda_g^* \sum_{k=0}^{j-2} \lambda_g^{*k} \\ &\quad + (1 - \lambda_g^*) E \left[E \left[\sum_{k=0}^{N_j} Y_{j,k} | R_s \right] \right] \\ &= \lambda_g^* \mu_0 + (1 - \lambda_g^*) \mu_0 + \mu_0 \frac{(1 - \lambda_g^*)}{1 - \gamma} \sum_{k=0}^{j-2} \lambda_g^{*k+1} \\ &\quad + (1 - \lambda_g^*) E \left[\sum_{k=0}^{N_j} E[Y_{j,k} | R_s] \right] \\ &= \mu_0 + \mu_0 \frac{(1 - \lambda_g^*)}{1 - \gamma} \sum_{k=0}^{j-2} \lambda_g^{*k+1} + (1 - \lambda_g^*) E[N_j] E[Y_{j,k}] \end{aligned}$$

due to Theorem 1 (by Klugman et al.)⁴¹ where $N_j \sim \text{geom}(1 - \gamma)$ and $Y_{j,k}$ is iid with μ_0 . Thus,

$$\begin{aligned} E[Z_j] &= \mu_0 + \mu_0 \frac{(1 - \lambda_g^*)}{1 - \gamma} \sum_{k=0}^{j-2} \lambda_g^{*k+1} + (1 - \lambda_g^*) \left(\frac{1}{1 - \gamma} \right) \mu_0 \\ &= \mu_0 \left(1 + \frac{1 - \lambda_g^*}{1 - \gamma} \left(\sum_{k=0}^{j-2} \lambda_g^{*k+1} + 1 \right) \right) \\ &= \mu_0 \left(1 + \frac{(1 - \lambda_g^*)}{1 - \gamma} \sum_{m=0}^{j-1} \lambda_g^{*m} \right). \end{aligned}$$

Since $0 < \lambda_g^* < 1$, we can also reexpress the above as follows:

$$\begin{aligned} E[Z_j] &= \mu_0 \left(1 + \frac{(1 - \lambda_g^*)}{1 - \gamma} \sum_{m=0}^{j-1} \lambda_g^{*m} \right) \\ &= \mu_0 \left(1 + \frac{(1 - \lambda_g^*)(1 - \lambda_g^{*j})}{1 - \gamma} \right) \\ &= \mu_0 \left(1 + \frac{1 - \lambda_g^{*j}}{1 - \gamma} \right). \end{aligned}$$

B) Asymptotic behaviour of the mean of Z_j .

Since $0 < \lambda_g^* < 1$, as j grows large, we have the following:

$$\begin{aligned} \lim_{j \rightarrow \infty} E[Z_j] &= \lim_{j \rightarrow \infty} \mu_0 \left(1 + \frac{1 - \lambda_g^{*j}}{1 - \gamma} \right) = \mu_0 \left(1 + \lim_{j \rightarrow \infty} \frac{1 - \lambda_g^{*j}}{1 - \gamma} \right) \\ &= \mu_0 \left(1 + \frac{1 - \lim_{j \rightarrow \infty} \lambda_g^{*j}}{1 - \gamma} \right) = \mu_0 \left(1 + \frac{1}{1 - \gamma} \right). \end{aligned}$$

C) Derivation of the variance of Z_j .

1) Variance of Z_1 .

$$\begin{aligned} \text{Var}[Z_1] &= \text{Var}[\lambda_g I_1 + (1 - \lambda_g) Z_0] = \text{Var}[\lambda_g^* Z_0 + (1 - \lambda_g^*) I_1] \\ &= \lambda_g^{*2} \text{Var}[Z_0] + (1 - \lambda_g^*)^2 \text{Var}(I_1) \text{ since } \text{Cov}(Z_0, I_1) = 0 \\ &= \lambda_g^{*2} \sigma_0^2 + (1 - \lambda_g^*)^2 \text{Var} \left(X_1 + \sum_{k=0}^{N_1} Y_{1,k} \right) \\ &= \lambda_g^{*2} \sigma_0^2 + (1 - \lambda_g^*)^2 \left(\text{Var}(X_1) + \text{Var} \left(\sum_{k=0}^{N_1} Y_{1,k} \right) \right) \\ &\quad \times \text{since } \text{Cov}(X_1, Y_{1,k}) = 0 \\ &= \lambda_g^{*2} \sigma_0^2 + (1 - \lambda_g^*)^2 \sigma_0^2 + (1 - \lambda_g^*)^2 (E(N_1) \text{Var}(Y_{1,k}) \\ &\quad + \text{Var}(N_1) (E(Y_{1,k}))^2) \end{aligned}$$

due to Theorem 1 (by Klugman et al.)⁴¹ where $N_1 \sim \text{geom}(1 - \gamma)$ and $Y_{1,k}$ is iid with mean μ_0 and variance σ_0^2 . Thus,

$$\begin{aligned} \text{Var}[Z_1] &= (\lambda_g^{*2} + (1 - \lambda_g^*)^2) \sigma_0^2 + (1 - \lambda_g^*)^2 \\ &\quad \left(\left(\frac{1}{1 - \gamma} \right) \sigma_0^2 + \frac{\gamma}{(1 - \gamma)^2} (\mu_0)^2 \right) \\ &= \left(\lambda_g^{*2} + (1 - \lambda_g^*)^2 \left(1 + \frac{1}{1 - \gamma} \right) \right) \sigma_0^2 \\ &\quad + \frac{\gamma (1 - \lambda_g^*)^2}{(1 - \gamma)^2} \mu_0^2. \end{aligned}$$

2) Variance of Z_2 .

$$\begin{aligned} \text{Var}[Z_2] &= \text{Var}[\lambda_g l_2 + (1 - \lambda_g)Z_1] = \text{Var}[\lambda_g^* Z_1 + (1 - \lambda_g^*) l_2] \\ &= \lambda_g^{*2} \text{Var}[Z_1] + (1 - \lambda_g^*)^2 \text{Var}(l_2) \text{ since } \text{Cov}(Z_1, l_2) = 0 \\ &= \lambda_g^{*2} \text{Var}[Z_1] + (1 - \lambda_g^*)^2 \text{Var} \left(X_2 + \sum_{k=0}^{N_2} Y_{2,k} \right) \\ &= \left(\lambda_g^{*4} + \lambda_g^{*2} (1 - \lambda_g^*)^2 \left(1 + \frac{1}{1 - \gamma} \right) \right) \sigma_0^2 \\ &\quad + \frac{\gamma \lambda_g^{*2} (1 - \lambda_g^*)^2}{(1 - \gamma)^2} \mu_0^2 \\ &\quad + (1 - \lambda_g^*)^2 \left(\text{Var}(X_2) + \text{Var} \left(\sum_{k=0}^{N_2} Y_{2,k} \right) \right) \\ &\quad \text{since } \text{Cov}(X_2, Y_{2,k}) = 0 \\ &= \left(\lambda_g^{*4} + \lambda_g^{*2} (1 - \lambda_g^*)^2 \left(1 + \frac{1}{1 - \gamma} \right) \right) \\ &\quad \times \sigma_0^2 + \frac{\gamma \lambda_g^{*2} (1 - \lambda_g^*)^2}{(1 - \gamma)^2} \mu_0^2 \\ &\quad + (1 - \lambda_g^*)^2 \sigma_0^2 + (1 - \lambda_g^*)^2 \\ &\quad \times (E(N_2) \text{Var}(Y_{2,k}) + \text{Var}(N_2) (E(Y_{2,k}))^2) \end{aligned}$$

due to Theorem 1 (by Klugman et al.)⁴¹ where $N_2 \sim \text{geom}(1 - \gamma)$ and $Y_{2,k}$ is iid with mean μ_0 and variance σ_0^2 . Thus,

$$\begin{aligned} \text{Var}[Z_2] &= \left(\lambda_g^{*4} + \lambda_g^{*2} (1 - \lambda_g^*)^2 \left(1 + \frac{1}{1 - \gamma} \right) + (1 - \lambda_g^*)^2 \right) \\ &\quad \times \sigma_0^2 + \frac{\gamma \lambda_g^{*2} (1 - \lambda_g^*)^2}{(1 - \gamma)^2} \mu_0^2 \\ &\quad + (1 - \lambda_g^*)^2 \left(\left(\frac{1}{1 - \gamma} \right) \sigma_0^2 + \frac{\gamma}{(1 - \gamma)^2} (\mu_0)^2 \right) \\ &= \left(\lambda_g^{*4} + (1 - \lambda_g^*)^2 \left(1 + \frac{1}{1 - \gamma} \right) (1 + \lambda_g^{*2}) \right) \sigma_0^2 \\ &\quad + \frac{\gamma}{(1 - \gamma)^2} (1 - \lambda_g^*)^2 (1 + \lambda_g^{*2}) \mu_0^2. \end{aligned}$$

3) Variance of Z_3 .

$$\text{Var}[Z_3] = \text{Var}[\lambda_g l_3 + (1 - \lambda_g)Z_2] = \text{Var}[\lambda_g^* Z_2 + (1 - \lambda_g^*) l_3]$$

With the independence of Z_2 and l_3 and independence of X_3 and $Y_{3,k}$ and by applying Theorem 1 (Klugman et al.)⁴¹ with simplification steps similar to the derivation of $\text{Var}[Z_2]$, we have,

$$\begin{aligned} \text{Var}[Z_3] &= \left(\lambda_g^{*6} + (1 - \lambda_g^*)^2 \left(1 + \frac{1}{1 - \gamma} \right) (1 + \lambda_g^{*2} (1 + \lambda_g^{*2})) \right) \\ &\quad \times \sigma_0^2 + \frac{\gamma}{(1 - \gamma)^2} (1 - \lambda_g^*)^2 (1 + \lambda_g^{*2} (1 + \lambda_g^{*2})) \mu_0^2. \end{aligned}$$

4) Variance of Z_j .

We now summarize the following results:

$$\begin{aligned} \text{Var}[Z_1] &= \left(\lambda_g^{*2} + (1 - \lambda_g^*)^2 \left(1 + \frac{1}{1 - \gamma} \right) \right) \\ &\quad \times \sigma_0^2 + \frac{\gamma (1 - \lambda_g^*)^2}{(1 - \gamma)^2} \mu_0^2, \end{aligned}$$

$$\begin{aligned} \text{Var}[Z_2] &= \left(\lambda_g^{*4} + (1 - \lambda_g^*)^2 \left(1 + \frac{1}{1 - \gamma} \right) (1 + \lambda_g^{*2}) \right) \\ &\quad \times \sigma_0^2 + \frac{\gamma}{(1 - \gamma)^2} (1 - \lambda_g^*)^2 (1 + \lambda_g^{*2}) \mu_0^2, \text{ and} \end{aligned}$$

$$\begin{aligned} \text{Var}[Z_3] &= \left(\lambda_g^{*6} + (1 - \lambda_g^*)^2 \left(1 + \frac{1}{1 - \gamma} \right) (1 + \lambda_g^{*2} (1 + \lambda_g^{*2})) \right) \\ &\quad \times \sigma_0^2 + \frac{\gamma}{(1 - \gamma)^2} (1 - \lambda_g^*)^2 (1 + \lambda_g^{*2} (1 + \lambda_g^{*2})) \mu_0^2. \end{aligned}$$

Based on the above, we now let

$$\begin{aligned} \text{Var}[Z_{j-1}] &= \left(\lambda_g^{*2(j-1)} + (1 - \lambda_g^*)^2 \left(1 + \frac{1}{1 - \gamma} \right) \sum_{k=0}^{j-2} \lambda_g^{*2k} \right) \\ &\quad \times \sigma_0^2 + \frac{\gamma}{(1 - \gamma)^2} (1 - \lambda_g^*)^2 \mu_0^2 \sum_{k=0}^{j-2} \lambda_g^{*2k}. \end{aligned}$$

Then by induction, we have

$$\begin{aligned} \text{Var}[Z_j] &= \text{Var}[\lambda_g l_j + (1 - \lambda_g)Z_{j-1}] = \text{Var}[\lambda_g^* Z_{j-1} + (1 - \lambda_g^*) l_j] \\ &= \lambda_g^{*2} \text{Var}[Z_{j-1}] + (1 - \lambda_g^*)^2 \\ &\quad \text{Var}(l_j) \text{ since } \text{Cov}(Z_{j-1}, l_j) = 0 \\ &= \lambda_g^{*2} \text{Var}[Z_{j-1}] + (1 - \lambda_g^*)^2 \text{Var} \left(X_j + \sum_{k=0}^{N_j} Y_{j,k} \right) \\ &= \left(\lambda_g^{*2j} + (1 - \lambda_g^*)^2 \left(1 + \frac{1}{1 - \gamma} \right) \lambda_g^{*2} \sum_{k=0}^{j-2} \lambda_g^{*2k} \right) \\ &\quad \times \sigma_0^2 + \frac{\gamma}{(1 - \gamma)^2} (1 - \lambda_g^*)^2 \mu_0^2 \sum_{k=0}^{j-2} \lambda_g^{*2(k+1)} \\ &\quad + (1 - \lambda_g^*)^2 \sigma_0^2 \\ &\quad + (1 - \lambda_g^*)^2 (E(N_j) \text{Var}(Y_{j,k}) + \text{Var}(N_j) (E(Y_{j,k}))^2) \end{aligned}$$

due to Theorem 1 (Klugman et al.)⁴¹ where $N_j \sim \text{geom}(1 - \gamma)$ and $Y_{j,k}$ is iid with mean μ_0 and variance σ_0^2 . Thus,

$$\begin{aligned} \text{Var}[Z_j] &= \left(\lambda_g^{*2j} + (1 - \lambda_g^*)^2 \left(1 + \frac{1}{1 - \gamma} \right) \right. \\ &\quad \left. \sum_{k=0}^{j-2} \lambda_g^{*2(k+1)} + (1 - \lambda_g^*)^2 \right) \\ &\quad \times \sigma_0^2 + \frac{\mu_0^2 \gamma}{(1 - \gamma)^2} (1 - \lambda_g^*)^2 \sum_{k=0}^{j-2} \lambda_g^{*2(k+1)} + (1 - \lambda_g^*)^2 \\ &\quad \times \left(\left(\frac{1}{1 - \gamma} \right) \sigma_0^2 + \frac{\gamma}{(1 - \gamma)^2} (\mu_0)^2 \right) \\ &= \left(\lambda_g^{*2j} + (1 - \lambda_g^*)^2 \left(1 + \sum_{k=0}^{j-2} \lambda_g^{*2(k+1)} \right) \left(1 + \frac{1}{1 - \gamma} \right) \right) \\ &\quad \times \sigma_0^2 + \frac{\gamma}{(1 - \gamma)^2} (1 - \lambda_g^*)^2 \left(1 + \sum_{k=0}^{j-2} \lambda_g^{*2(k+1)} \right) \mu_0^2 \\ &= \left(\lambda_g^{*2j} + (1 - \lambda_g^*)^2 \left(1 + \frac{1}{1 - \gamma} \right) \left(\sum_{m=0}^{j-1} \lambda_g^{*2m} \right) \right) \\ &\quad \times \sigma_0^2 + \frac{\gamma}{(1 - \gamma)^2} (1 - \lambda_g^*)^2 \left(\sum_{m=0}^{j-1} \lambda_g^{*2m} \right) \mu_0^2. \end{aligned}$$

Since $0 < \lambda_g^{*2} \leq 1$, we can also reexpress the above as follows:

$$\begin{aligned} \text{Var}[Z_j] &= \left(\lambda_g^{*2j} + (1 - \lambda_g^*)^2 \left(\frac{1 - \lambda_g^{*2j}}{1 - \lambda_g^{*2}} \right) \left(1 + \frac{1}{1 - \gamma} \right) \right) \\ &\quad \times \sigma_0^2 + \frac{\gamma}{(1 - \gamma)^2} (1 - \lambda_g^*)^2 \left(\frac{1 - \lambda_g^{*2j}}{1 - \lambda_g^{*2}} \right) \mu_0^2. \end{aligned}$$

D) Asymptotic behaviour of the variance of Z_j .

Since $0 < \lambda_g^* \leq 1$, as j grows large we have the following:

$$\begin{aligned} \lim_{j \rightarrow \infty} \text{Var}[Z_j] &= \lim_{j \rightarrow \infty} \left(\lambda_g^{*2j} + \left(1 + \frac{1}{1 - \gamma} \right) (1 - \lambda_g^*)^2 \left(\frac{1 - \lambda_g^{*2j}}{1 - \lambda_g^{*2}} \right) \right) \\ &\quad \times \sigma_0^2 + \lim_{j \rightarrow \infty} \frac{\gamma}{(1 - \gamma)^2} (1 - \lambda_g^*)^2 \left(\frac{1 - \lambda_g^{*2j}}{1 - \lambda_g^{*2}} \right) \mu_0^2 \end{aligned}$$

$$\begin{aligned} &= \sigma_0^2 \lim_{j \rightarrow \infty} (\lambda_g^{*2j}) + \sigma_0^2 \left(\left(1 + \frac{1}{1 - \gamma} \right) \lim_{j \rightarrow \infty} (1 - \lambda_g^*)^2 \right. \\ &\quad \left. \times \left(\frac{1 - \lambda_g^{*2j}}{(1 + \lambda_g^*)(1 - \lambda_g^*)} \right) \right) \\ &\quad + \frac{\gamma}{(1 - \gamma)^2} (1 - \lambda_g^*)^2 \left(\frac{1 - \lim_{j \rightarrow \infty} \lambda_g^{*2j}}{(1 + \lambda_g^*)(1 - \lambda_g^*)} \right) \mu_0^2 \\ &= \left(1 + \frac{1}{1 - \gamma} \right) \left(\frac{1 - \lambda_g^*}{1 + \lambda_g^*} \right) \sigma_0^2 + \frac{\gamma}{(1 - \gamma)^2} \left(\frac{1 - \lambda_g^*}{1 + \lambda_g^*} \right) \mu_0^2. \end{aligned}$$